Fast Second-Order Evaluation for Variable-Order Caputo Fractional Derivative with Applications to Fractional Sub-Diffusion Equations

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Abstract. In this paper, we propose a fast second-order approximation to the variable-order (VO) Caputo fractional derivative, which is developed based on $L2-1_{\sigma}$ formula and the exponential-sum-approximation technique. The fast evaluation method can achieve the second-order accuracy and further reduce the computational cost and the acting memory for the VO Caputo fractional derivative. This fast algorithm is applied to construct a relevant fast temporal second-order and spatial fourth-order scheme ($FL2-1_{\sigma}$ scheme) for the multi-dimensional VO time-fractional sub-diffusion equations. Theoretically, $FL2-1_{\sigma}$ scheme is proved to fulfill the similar properties of the coefficients as those of the well-studied $L2-1_{\sigma}$ scheme. Therefore, $FL2-1_{\sigma}$ scheme is strictly proved to be unconditionally stable and convergent. A sharp decrease in the computational cost and the acting memory is shown in the numerical examples to demonstrate the efficiency of the proposed method.

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Key words: Variable-order Caputo fractional derivative, exponential-sum-approximation method, fast algorithm, time-fractional sub-diffusion equation, stability and convergence.

1. Introduction

Over the last few decades, the fractional calculus has gained much attention of both mathematics and physical science due to the non-locality of fractional operators. In fact the fractional calculus has been widely applied in various fields including the biology, the ecology, the diffusion, and the control system [3, 15, 19, 21, 27, 29–31]. Recently, more and more researchers revealed that many important dynamical problems exhibit the fractional order behavior that may vary with time, space, or some other factors, which leads to the concept of the variable-order (VO) fractional operator, see [13, 22,

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38,40]. This fact indicates that the VO fractional calculus is an expected tool to provide an effective mathematical framework to characterize the complex problems in fields of science and engineering; for instances, anomalous diffusion [7, 8, 39, 45], viscoelastic mechanics [9, 10, 16, 35], and petroleum engineering [28].

The VO fractional derivative can be regarded as an extension of the constant-order (CO) fractional derivative [41]. An interesting extension of the classical fractional calculus was proposed by Samko and Ross [33] in which they generalized the Riemann-Liouville and Marchaud fractional operators in the VO case. Later, Lorenzo and Hartley [22] first introduced the concept of VO operators. According to the concept, the order of the operator is allowed to vary as a function of independent variables such as time and space. Afterwards, various VO differential operators with specific meanings were defined. Coimbra [9] gave a novel definition for the VO differential operator by taking the Laplace-transform of the Caputo's definition of the fractional derivative. Soon, Coimbra, and Kobayashi [36] showed that Coimbra's definition was better suited for modeling physical problems due to its meaningful physical interpretations, see also [32]. Moreover, the Coimbra's VO fractional derivative could be considered as the Caputo-type definition, which is defined as follows [9, 38]:

$${}_{0}^{C}\mathcal{D}_{t}^{\alpha(t)}u(t) \equiv \frac{1}{\Gamma(1-\alpha(t))} \int_{0}^{t} \frac{u'(\tau)}{(t-\tau)^{\alpha(t)}} \mathrm{d}\tau,$$
(1.1)

where $\Gamma(\cdot)$ denotes the Gamma function and $\alpha(t) \in [\underline{\alpha}, \overline{\alpha}] \subset (0, 1)$ is the VO function. We remark that, in statistical physics community, the operator (1.1) has clear physical meaning if α is a function of the space variable x (see [13]), while the physical significance for the case of $\alpha(t)$ is still unclear. Nonetheless, the operator (1.1) has been widely used to model some phenomena in engineering community [9,38].

Since the problems described by the VO fractional operator are difficult to handle analytically, possible numerical implementations of the VO fractional problems are given. In [44], Zhao *et al.* derived two second-order approximations for the VO Caputo fractional derivative and provided the error analysis. For the VO time-fractional sub-diffusion equations, Du *et al.* [11] proposed L2-1 $_{\sigma}$ scheme, which makes use of the piecewise high-order polynomial interpolation of the solution. The resulting method was investigated to be unconditionally stable and second-order convergent via the energy method.

In consequence of the nonlocal property and historical dependence of the fractional operators, the aforementioned numerical methods always require all previous function values, which leads to an average O(n) storage and computational cost $O(n^2)$, where n is the total number of the time levels. To overcome this difficulty, many efforts have been made to speed up the evaluation of the CO fractional derivative [2, 4, 14, 17, 18, 23–25, 42]. Nevertheless, the coefficient matrices of the numerical schemes for the VO fractional problems lose the Toeplitz-like structure and the VO fractional derivative is no longer a convolution operator. Therefore, those fast methods for the CO fractional derivative and the VO fractional derivative fast algorithm for the VO Caputo fractional derivative based on a shifted binary block

partition and uniform polynomial approximations of degree r. Compared with the general direct method, the proposed algorithm reduces the memory requirement from $\mathcal{O}(n)$ to $\mathcal{O}(r \log n)$ and the complexity from $\mathcal{O}(n^2)$ to $\mathcal{O}(rn \log n)$. Zhang *et al.* [43] developed an exponential-sum-approximation (ESA) technique to speed up L1 formula for the VO Caputo fractional derivative. The proposed method reduces the storage requirement to $\mathcal{O}(\log^2 n)$ and the computational cost to $\mathcal{O}(n \log^2 n)$, respectively. Both of those fast methods were proved to achieve the convergence order of $2 - \overline{\alpha}$ with expected parameters.

Motivated by the need of fast high-order approaches for the VO Caputo fractional derivative (1.1), we combine $L2 \cdot 1_{\sigma}$ formula [11] with the ESA technique [43] to produce a fast evaluation formula, which is called $FL2 \cdot 1_{\sigma}$ formula later. Compared with $L2 \cdot 1_{\sigma}$ formula, the fast algorithm reduces the acting memory from $\mathcal{O}(n)$ to $\mathcal{O}(\log^2 n)$ and flops from $\mathcal{O}(n^2)$ to $\mathcal{O}(n \log^2 n)$. Then $FL2 \cdot 1_{\sigma}$ formula is applied to construct a fast temporal second-order and spatial fourth-order difference scheme ($FL2 \cdot 1_{\sigma}$ scheme) for the multi-dimensional VO time-fractional sub-diffusion equations, which significantly reduces the memory requirement and computational complexity. We present the properties of the coefficients of $FL2 \cdot 1_{\sigma}$ formula, which ensure the stability and the convergence of the proposed scheme. Numerical experiments are provided to show the sharp decrease in the CPU time and storage of the fast algorithm with the same accuracy as the direct method. Moreover, we test the proposed scheme on the graded mesh, and it performs well while the solution has singularity.

The paper is organized as follows. In Section 2, we present FL2-1 $_{\sigma}$ formula approaching the VO Caputo fractional derivative utilizing the ESA technique. Then we construct FL2-1 $_{\sigma}$ scheme for multi-dimensional VO fractional sub-diffusion problems in Section 3 and investigate the stability and convergence. In Section 4, reliability and efficiency are confirmed by some numerical examples. Concluding remarks are given in Section 5.

2. Approximation for VO fractional derivative

We firstly introduce $L2 \cdot 1_{\sigma}$ formula [11] for the VO Caputo fractional derivative. Consider the VO Caputo fractional derivative defined by (1.1) with $t \in (0,T]$ $(T \ge 1)$. For a positive integer n, let $\Delta t = T/n$ and $t_k = k\Delta t$ for k = 0, 1, ..., n. We denote $t_{k+\sigma_k} = t_k + \sigma(t_k)\Delta t$ for k = 0, 1, ..., n - 1. The parameter $\sigma(t_k)$ is determined by the equation

$$F(\sigma) = \sigma - \left(1 - \frac{1}{2}\alpha(t_k + \sigma\Delta t)\right) = 0,$$

which has a unique root $\sigma(t_k) \in (\frac{1}{2}, 1)$ being conveniently calculated by Newton's method [11]. In the following, we denote $\sigma_k = \sigma(t_k)$, $\alpha_{k+\sigma_k} = \alpha(t_{k+\sigma_k})$.

From the definition (1.1), the VO Caputo derivative at the point $t_{k+\sigma_k}$ is presented as

$${}_{0}^{C}\mathcal{D}_{t}^{\alpha(t)}u(t)|_{t=t_{k+\sigma_{k}}} = \frac{1}{\Gamma\left(1-\alpha_{k+\sigma_{k}}\right)} \int_{0}^{t_{k+\sigma_{k}}} \frac{u'(\tau)}{\left(t_{k+\sigma_{k}}-\tau\right)^{\alpha_{k+\sigma_{k}}}} \mathrm{d}\tau.$$
 (2.1)

To discretize the VO Caputo fractional derivative, we denote the quadric interpolation on the time interval $[t_{k-1}, t_k]$ with $1 \le k \le n-1$ and the linear interpolation over the time interval $[t_k, t_{k+1}]$ with $0 \le k \le n-1$ by

$$L_2 u(\tau) = \sum_{p=-1}^{1} u(t_{k+p}) \prod_{q=-1}^{1} \frac{\tau - t_{k+q}}{t_{k+p} - t_{k+q}}, \qquad \tau \in [t_{k-1}, t_k],$$
(2.2)

$$L_1 u(\tau) = u(t_k) \frac{\tau - t_{k+1}}{t_k - t_{k+1}} + u(t_{k+1}) \frac{\tau - t_k}{t_{k+1} - t_k}, \quad \tau \in [t_k, t_{k+1}].$$
(2.3)

2.1. L2-1 $_{\sigma}$ formula

Based on the above interpolation polynomials, at time $t_{k+\sigma_k}$ with k = 0, 1, ..., n-1, $L2-1_{\sigma}$ approximation formula to (2.1) is obtained as [11]

where $g_0^{(0)} = \sigma_0^{1-\alpha_{\sigma_0}}$, and for $k \ge 1$,

The following lemma shows the local truncation error of L2-1 $_{\sigma}$ approximation formula for the VO Caputo fractional derivative.

Lemma 2.1 ([11]). Suppose $u \in C^3([0, t_{k+1}])$. Let

$$r^{k} = \Big| {}_{0}^{C} \mathcal{D}_{t}^{\alpha(t)} u(t) |_{t=t_{k+\sigma_{k}}} - {}_{0}^{H} \mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}} u(t_{k+\sigma_{k}}) \Big|.$$

Then, we have

$$|r^{k}| \leq \frac{\max_{0 \leq t \leq t_{k+1}} |u^{(3)}(t)| \sigma_{k}^{-\alpha_{k+\sigma_{k}}}}{\Gamma(1-\alpha_{k+\sigma_{k}})} \left(\frac{1}{12} + \frac{\sigma_{k}}{6(1-\alpha_{k+\sigma_{k}})}\right) \Delta t^{3-\alpha_{k+\sigma_{k}}}.$$

Utilizing $L2 \cdot 1_{\sigma}$ approximation formula to calculate the value at the current time level, it needs to compute the summation of a series including the values of all previous time levels. Therefore, $L2 \cdot 1_{\sigma}$ approximation formula requires $\mathcal{O}(n)$ storage and $\mathcal{O}(n^2)$ computational complexity. It inspires us to construct a fast algorithm to approach $L2 \cdot 1_{\sigma}$ approximation formula (2.4).

2.2. FL2-1 $_{\sigma}$ formula

Now, we develop a fast high-order numerical formula (FL2-1 $_{\sigma}$ formula) for the VO Caputo fractional derivative. The kernel function in the VO Caputo fractional derivative is approximated by the ESA technique, which is stated in [5, 43].

Lemma 2.2. For any constant $\alpha_{k+\sigma_k} \in [\underline{\alpha}, \overline{\alpha}] \subset (0, 1)$, $0 < \Delta t/T \leq (t_{k+\sigma_k} - \tau)/T \leq 1$ for $\tau \in [0, t_{k-1}]$, $1 \leq k \leq n-1$ and the expected accuracy $0 < \epsilon \leq 1/e$, there exist a constant h, integers \overline{N} and \underline{N} , which satisfy

$$h = \frac{2\pi}{\log 3 + \overline{\alpha} \log(\cos 1)^{-1} + \log \epsilon^{-1}},$$

$$\underline{N} = \left[\frac{1}{h}\frac{1}{\underline{\alpha}} \left(\log \epsilon + \log \Gamma(1 + \overline{\alpha})\right)\right],$$

$$\overline{N} = \left\lfloor\frac{1}{h}\left(\log \frac{T}{\Delta t} + \log \log \epsilon^{-1} + \log \underline{\alpha} + 2^{-1}\right)\right\rfloor,$$

(2.5)

such that

$$\left(\frac{t_{k+\sigma_k}-\tau}{T}\right)^{-\alpha_{k+\sigma_k}} - \sum_{i=\underline{N}+1}^{\overline{N}} \theta_i^{(k)} e^{\frac{-\lambda_i(t_{k+\sigma_k}-\tau)}{T}} \right| \le \left(\frac{t_{k+\sigma_k}-\tau}{T}\right)^{-\alpha_{k+\sigma_k}} \epsilon, \quad (2.6)$$

where the quadrature exponents and weights are given by

$$\lambda_i = e^{ih}, \quad \theta_i^{(k)} = \frac{h e^{\alpha_{k+\sigma_k}ih}}{\Gamma(\alpha_{k+\sigma_k})}.$$

Now $L2-1_{\sigma}$ formula (2.4) can be approximated by

$$= \frac{1}{\Gamma(1 - \alpha_{k+\sigma_{k}})} \left(\int_{0}^{t_{k}} \frac{\left(L_{2}u(\tau)\right)'}{T^{\alpha_{k+\sigma_{k}}}} \left(\frac{t_{k+\sigma_{k}} - \tau}{T}\right)^{-\alpha_{k+\sigma_{k}}} \mathrm{d}\tau + \int_{t_{k}}^{t_{k+\sigma_{k}}} \frac{\left(L_{1}u(\tau)\right)'}{\left(t_{k+\sigma_{k}} - \tau\right)^{\alpha_{k+\sigma_{k}}}} \mathrm{d}\tau \right)$$

$$\approx \frac{1}{\Gamma(1-\alpha_{k+\sigma_{k}})}$$

$$\times \left(\int_{0}^{t_{k}} \frac{\left(L_{2}u(\tau)\right)'}{T^{\alpha_{k+\sigma_{k}}}} \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} d\tau + \int_{t_{k}}^{t_{k+\sigma_{k}}} \frac{\left(L_{1}u(\tau)\right)'}{\left(t_{k+\sigma_{k}}-\tau\right)^{\alpha_{k+\sigma_{k}}}} d\tau \right)$$

$$= \frac{T^{-\alpha_{k+\sigma_{k}}}}{\Gamma(1-\alpha_{k+\sigma_{k}})} \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} \int_{0}^{t_{k}} \left(L_{2}u(\tau)\right)' e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} d\tau$$

$$+ \frac{u(t_{k+1})-u(t_{k})}{\Delta t\Gamma(1-\alpha_{k+\sigma_{k}})} \int_{t_{k}}^{t_{k+\sigma_{k}}} \frac{1}{\left(t_{k+\sigma_{k}}-\tau\right)^{\alpha_{k+\sigma_{k}}}} d\tau$$

$$= \frac{T^{-\alpha_{k+\sigma_{k}}}}{\Gamma(1-\alpha_{k+\sigma_{k}})} \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} H_{i}^{(k)} + s^{(k)} \sigma_{k}^{1-\alpha_{k+\sigma_{k}}} \left(u(t_{k+1})-u(t_{k})\right), \qquad (2.7)$$

where $H_i^{(k)}$ is the history part of the integral,

$$H_i^{(k)} = \int_0^{t_k} \left(L_2 u(\tau) \right)' e^{\frac{-\lambda_i (t_{k+\sigma_k} - \tau)}{T}} \mathrm{d}\tau.$$

We point out that ${\cal H}_i^{(k)}$ can be calculated by a recursive relation and quadratic interpolation, i.e.,

$$H_{i}^{(k)} = e^{\frac{-\lambda_{i}(1+\sigma_{k}-\sigma_{k-1})\Delta t}{T}} H_{i}^{(k-1)} + \int_{t_{k-1}}^{t_{k}} \left(L_{2}u(\tau)\right)' e^{\frac{-\lambda_{i}(t_{k}+\sigma_{k}-\tau)}{T}} d\tau$$
(2.8)
$$= e^{\frac{-\lambda_{i}(1+\sigma_{k}-\sigma_{k-1})\Delta t}{T}} H_{i}^{(k-1)} + A_{i}^{(k)} \left(u(t_{k}) - u(t_{k-1})\right) + B_{i}^{(k)} \left(u(t_{k+1}) - u(t_{k})\right)$$

with $H_i^{(0)} = 0$ $(i = \underline{N} + 1, \dots, \overline{N})$ and

$$\begin{split} A_i^{(k)} &= \frac{1}{\Delta t^2} \int_{t_{k-1}}^{t_k} (t_{k+\frac{1}{2}} - \tau) e^{\frac{-\lambda_i (t_k + \sigma_k - \tau)}{T}} \mathrm{d}\tau \\ &= \int_{k-1}^k \left(k + \frac{1}{2} - \tau\right) e^{\frac{-\lambda_i (k + \sigma_k - \tau)\Delta t}{T}} \mathrm{d}\tau \\ &= \int_0^1 \left(\frac{3}{2} - \tau\right) e^{\frac{-\lambda_i (\sigma_k + 1 - \tau)\Delta t}{T}} \mathrm{d}\tau, \\ B_i^{(k)} &= \frac{1}{\Delta t^2} \int_{t_{k-1}}^{t_k} (\tau - t_{k-\frac{1}{2}}) e^{\frac{-\lambda_i (t_k + \sigma_k - \tau)}{T}} \mathrm{d}\tau \\ &= \int_{k-1}^k \left(\tau - k + \frac{1}{2}\right) e^{\frac{-\lambda_i (\kappa + \sigma_k - \tau)\Delta t}{T}} \mathrm{d}\tau, \\ &= \int_0^1 \left(\tau - \frac{1}{2}\right) e^{\frac{-\lambda_i (\sigma_k + 1 - \tau)\Delta t}{T}} \mathrm{d}\tau, \end{split}$$

where we use (2.2) and the transformation of the integration variable.

J.-L. Zhang, Z.-W. Fang and H.-W. Sun

Overall, for $0 \le k \le n-1$, we define $FL2-1_{\sigma}$ formula for ${}_{0}^{C}\mathcal{D}_{t}^{\alpha(t)}u(t)|_{t=t_{k+\sigma_{k}}}$ by

$$= \frac{T^{-\alpha_{k+\sigma_{k}}}}{\Gamma(1-\alpha_{k+\sigma_{k}})} \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} H_{i}^{(k)} + s^{(k)} \sigma_{k}^{1-\alpha_{k+\sigma_{k}}} \left(u(t_{k+1}) - u(t_{k}) \right),$$
(2.9)

where $H_i^{(k)}$ is calculated by (2.8). In addition, for k = 0, we let

$${}^{FH}_{0}\mathcal{D}^{\alpha_{\sigma_0}}_t u(t_{\sigma_0}) = {}^{H}_{0}\mathcal{D}^{\alpha_{\sigma_0}}_t u(t_{\sigma_0}).$$
(2.10)

We give the following lemma to state the local truncated error of FL2-1 $_{\sigma}$ formula (2.9) for the VO Caputo fractional derivative ${}_{0}^{C}\mathcal{D}_{t}^{\alpha(t)}u(t)|_{t=t_{k+\sigma_{k}}}$.

Lemma 2.3. Suppose $\alpha_{k+\sigma_k} \in (0,1)$ and $u(t) \in C^3([0,T])$. Let $L2 \cdot 1_{\sigma}$ formula be as in (2.4), $FL2 \cdot 1_{\sigma}$ formula be defined by (2.9)-(2.10) and ϵ be the expected accuracy. Then, we have

Proof. Clearly, (2.10) and Lemma 2.1 imply the lemma is valid for k = 0. For $k \ge 1$, according to (2.7) and (2.9), ${}^{H}_{0}\mathcal{D}^{\alpha_{k+\sigma_{k}}}_{t}u(t_{k+\sigma_{k}})$ and ${}^{FH}_{0}\mathcal{D}^{\alpha_{k+\sigma_{k}}}_{t}u(t_{k+\sigma_{k}})$ just differ in the approximation for $(\frac{t_{k+\sigma_{k}}-\tau}{T})^{-\alpha_{k+\sigma_{k}}}, \tau \in (0, t_{k+\sigma_{k}})$, i.e.,

$$\begin{split} & \left| {}_{0}^{C} \mathcal{D}_{t}^{\alpha(t)} u(t) \right|_{t=t_{k+\sigma_{k}}} - {}_{0}^{FH} \mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}} u(t_{k+\sigma_{k}}) \right| \\ & \leq \left| {}_{0}^{C} \mathcal{D}_{t}^{\alpha(t)} u(t) \right|_{t=t_{k+\sigma_{k}}} - {}_{0}^{H} \mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}} u(t_{k+\sigma_{k}}) \right| \\ & + \left| {}_{0}^{H} \mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}} u(t_{k+\sigma_{k}}) - {}_{0}^{FH} \mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}} u(t_{k+\sigma_{k}}) \right| \\ & = \mathcal{O} \left(\Delta t^{3-\alpha_{k+\sigma_{k}}} \right) + \frac{T^{-\alpha_{k+\sigma_{k}}}}{\Gamma(1-\alpha_{k+\sigma_{k}})} \\ & \times \sum_{l=1}^{k} \int_{t_{l-1}}^{t_{l}} \left| \left(\frac{t_{k+\sigma_{k}} - \tau}{T} \right)^{-\alpha_{k+\sigma_{k}}} - \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}} - \tau)}{T}} \right| (L_{2}u(\tau))' \mathrm{d}\tau \\ & = \mathcal{O} \left(\Delta t^{3-\alpha_{k+\sigma_{k}}} \right) + \frac{t_{k+\sigma_{k}}^{1-\alpha_{k+\sigma_{k}}} \max_{0 \leq t \leq t_{k}} |u'(t)|}{\Gamma(2-\alpha_{k+\sigma_{k}})} \mathcal{O}(\epsilon). \end{split}$$

Since $t_{k+\sigma_k} \leq T$ and $u(t) \in C^3([0,T])$, the proof is complete.

From Lemma 2.3, we conclude that the approximation for the VO Caputo fractional derivative ${}_{0}^{C}\mathcal{D}_{t}^{\alpha(t)}u(t)$ at the point $t_{k+\sigma_{k}}$ by ${}_{0}^{FH}\mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}}u(t_{k+\sigma_{k}})$ is at least second-order precision with sufficiently small ϵ .

2.3. Properties of discrete kernels

In order to prepare the subsequent analysis, we firstly show the properties of discrete kernels in FL2-1 $_{\sigma}$ formula. The recursive relation of $H_i^{(k)}$ defined in (2.8) can be equivalently rewritten as

$$\begin{aligned} H_{i}^{(k)} &= \sum_{l=1}^{k} \int_{t_{l-1}}^{t_{l}} \left(L_{2}u(\tau) \right)' e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} \mathrm{d}\tau \\ &= \Delta t^{-2} \Biggl\{ \int_{t_{0}}^{t_{1}} (t_{\frac{3}{2}} - \tau) e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} \mathrm{d}\tau \left(u(t_{1}) - u(t_{0}) \right) \\ &+ \sum_{l=1}^{k-1} \Biggl[\int_{t_{l-1}}^{t_{l}} (\tau - t_{l-\frac{1}{2}}) e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} \mathrm{d}\tau + \int_{t_{l}}^{t_{l+1}} (t_{l+\frac{3}{2}} - \tau) e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} \mathrm{d}\tau \Biggr] \\ &\times \left(u(t_{l+1}) - u(t_{l}) \right) + \int_{t_{k-1}}^{t_{k}} (\tau - t_{k-\frac{1}{2}}) e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} \mathrm{d}\tau \left(u(t_{k+1}) - u(t_{k}) \right) \Biggr\}, \end{aligned}$$

which allows to represent ${}^{FH}_{0}\mathcal{D}^{\alpha_{k+\sigma_k}}_tu(t_{k+\sigma_k}) \; (0\leq k\leq n-1)$ in the form

$$F_{0}^{H} \mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}} u(t_{k+\sigma_{k}})$$

$$= \frac{T^{-\alpha_{k+\sigma_{k}}} \Delta t^{-2}}{\Gamma(1-\alpha_{k+\sigma_{k}})} \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} \Biggl\{ \int_{t_{0}}^{t_{1}} (t_{\frac{3}{2}}-\tau) e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} d\tau (u(t_{1})-u(t_{0})) \\
+ \sum_{l=1}^{k-1} \Biggl[\int_{t_{l-1}}^{t_{l}} (\tau-t_{l-\frac{1}{2}}) e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} d\tau + \int_{t_{l}}^{t_{l+1}} (t_{l+\frac{3}{2}}-\tau) e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} d\tau \Biggr] \\
\times (u(t_{l+1})-u(t_{l})) + \int_{t_{k-1}}^{t_{k}} (\tau-t_{k-\frac{1}{2}}) e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} d\tau (u(t_{k+1})-u(t_{k})) \Biggr\} \\
+ s^{(k)} \sigma_{k}^{1-\alpha_{k+\sigma_{k}}} (u(t_{k+1})-u(t_{k})) \\
= s^{(k)} \sum_{l=0}^{k} \rho_{l}^{(k)} (u(t_{k-l+1})-u(t_{k-l})), \qquad (2.12)$$

where

$$\rho_0^{(0)} = \sigma_0^{1 - \alpha_{\sigma_0}},\tag{2.13}$$

and for $1 \le k \le n-1$,

$$\rho_l^{(k)} = \frac{1 - \alpha_{k+\sigma_k}}{T^{\alpha_{k+\sigma_k}} \Delta t^{2-\alpha_{k+\sigma_k}}}$$

$$\begin{cases} \int_{t_{k-1}}^{t_{k}} (\tau - t_{k-\frac{1}{2}}) \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} e^{\frac{-\lambda_{i}(t_{k}+\sigma_{k}-\tau)}{T}} d\tau \\ + T^{\alpha_{k+\sigma_{k}}} \int_{t_{k}}^{t_{k+\sigma_{k}}} \frac{\Delta t}{(t_{k+\sigma_{k}}-\tau)^{\alpha_{k+\sigma_{k}}}} d\tau, \qquad l = 0, \\ \int_{t_{k-l-1}}^{t_{k-l}} (\tau - t_{k-l-\frac{1}{2}}) \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} d\tau \\ + \int_{t_{k-l}}^{t_{k-l+1}} (t_{k-l+\frac{3}{2}}-\tau) \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} d\tau, \qquad 1 \le l \le k-1, \\ \int_{t_{0}}^{t_{1}} (t_{\frac{3}{2}}-\tau) \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}}-\tau)}{T}} d\tau, \qquad l = k. \end{cases}$$

The coefficients $\{\rho_l^{(k)}|0 \le l \le k; 0 \le k \le n-1\}$ defined in (2.13) and (2.14) have the following properties, which play the vital roles in studying the stability and convergence of the finite difference schemes. Below we present the relationship between $\rho_l^{(k)}$ and $g_l^{(k)}$.

Lemma 2.4. For $\alpha_{k+\sigma_k} \in (0,1)$, $g_l^{(k)}$ $(0 \le l \le k; 0 \le k \le n-1)$ defined in (2.4), $\rho_l^{(k)}$ $(0 \le l \le k; 0 \le k \le n-1)$ defined in (2.13) and (2.14) with $\sigma_k = 1 - \frac{\alpha_{k+\sigma_k}}{2}$. Then, we have $p_0^{(0)} = g_0^{(0)},$

$$\rho_0^{(0)} = g_0^{(0)}$$

and for $1 \leq k \leq n-1$,

$$\left|\rho_{l}^{(k)} - g_{l}^{(k)}\right| \leq \frac{1 - \alpha_{k+\sigma_{k}}}{\Delta t^{\alpha_{k+\sigma_{k}}}} \begin{cases} \frac{\epsilon}{4}, & l = 0, \\ \frac{5\epsilon}{4}, & 1 \leq l \leq k-1, \\ \epsilon, & l = k. \end{cases}$$
(2.15)

Proof. For k = 0, $\rho_0^{(0)} = g_0^{(0)}$ is obvious. For $k \ge 1$, the ESA approximation (2.6) with (2.4) and (2.12) gives

$$\begin{aligned} \left| \rho_0^{(k)} - g_0^{(k)} \right| &\leq \frac{\Delta t^{\alpha_{k+\sigma_k} - 2} (1 - \alpha_{k+\sigma_k})}{T^{\alpha_{k+\sigma_k}}} \\ &\times \left\{ \int_{t_{k-1}}^{t_k} \left| \tau - t_{k-\frac{1}{2}} \right| \cdot \left| \left(\frac{t_{k+\sigma_k} - \tau}{T} \right)^{-\alpha_{k+\sigma_k}} - \sum_{i=\underline{N}+1}^{\overline{N}} \theta_i^{(k)} e^{\frac{-\lambda_i (t_{k+\sigma_k} - \tau)\Delta t}{T}} \right| \mathrm{d}\tau \right\} \\ &\leq \Delta t^{\alpha_{k+\sigma_k} - 2} (1 - \alpha_{k+\sigma_k}) \epsilon \int_{t_{k-1}}^{t_k} \left| \tau - t_{k-\frac{1}{2}} \right| (t_{k+\sigma_k} - \tau)^{-\alpha_{k+\sigma_k}} \mathrm{d}\tau \\ &= (1 - \alpha_{k+\sigma_k}) \epsilon \int_0^1 \left| \tau - \frac{1}{2} \right| (\sigma_k - \tau + 1)^{-\alpha_{k+\sigma_k}} \mathrm{d}\tau \end{aligned}$$

$$\leq (1 - \alpha_{k+\sigma_k}) \Delta t^{-\alpha_{k+\sigma_k}} \epsilon \cdot \int_0^1 \left| \tau - \frac{1}{2} \right| \mathrm{d}\tau = \frac{\epsilon}{4} (1 - \alpha_{k+\sigma_k}) \Delta t^{-\alpha_{k+\sigma_k}}.$$

For $1 \leq l \leq k - 1$, we obtain

$$\begin{split} \left| \rho_{l}^{(k)} - g_{l}^{(k)} \right| &\leq \frac{\Delta t^{\alpha_{k} + \sigma_{k}}^{-2} (1 - \alpha_{k} + \sigma_{k})}{T^{\alpha_{k} + \sigma_{k}}} \\ &\times \left\{ \int_{t_{k-l-1}}^{t_{k-l}} \left| \tau - t_{k-l-\frac{1}{2}} \right| \cdot \left| \left(\frac{t_{k} + \sigma_{k} - \tau}{T} \right)^{-\alpha_{k} + \sigma_{k}} - \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} e^{\frac{-\lambda_{i}(t_{k} + \sigma_{k} - \tau)\Delta t}{T}} \right| \mathrm{d}\tau \right. \\ &+ \int_{t_{k-l}}^{t_{k-l+1}} \left| t_{k-l+\frac{3}{2}} - \tau \right| \left| \left(\frac{t_{k} + \sigma_{k} - \tau}{T} \right)^{-\alpha_{k} + \sigma_{k}} - \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} e^{\frac{-\lambda_{i}(t_{k} + \sigma_{k} - \tau)\Delta t}{T}} \right| \mathrm{d}\tau \right\} \\ &\leq \Delta t^{\alpha_{k} + \sigma_{k} - 2} (1 - \alpha_{k} + \sigma_{k}) \epsilon \left\{ \int_{t_{k-l-1}}^{t_{k-l}} \left| \tau - t_{k-l-\frac{1}{2}} \right| (t_{k} + \sigma_{k} - \tau)^{-\alpha_{k} + \sigma_{k}} \mathrm{d}\tau \right. \\ &+ \int_{t_{k-l}}^{t_{k-l+1}} \left| t_{k-l+\frac{3}{2}} - \tau \right| (t_{k} + \sigma_{k} - \tau)^{-\alpha_{k} + \sigma_{k}} \mathrm{d}\tau \right\} \\ &= (1 - \alpha_{k} + \sigma_{k}) \epsilon \left\{ \int_{0}^{1} \left| \tau - \frac{1}{2} \right| (\sigma_{k} - \tau + l + 1)^{-\alpha_{k} + \sigma_{k}} \mathrm{d}\tau \right\} \\ &\leq (1 - \alpha_{k} + \sigma_{k}) \Delta t^{-\alpha_{k} + \sigma_{k}} \epsilon \left\{ \int_{0}^{1} \left| \frac{3}{2} - \tau \right| \mathrm{d}\tau + \int_{0}^{1} \left| \tau - \frac{1}{2} \right| \mathrm{d}\tau \right\} = \frac{5\epsilon}{4} (1 - \alpha_{k} + \sigma_{k}) \Delta t^{-\alpha_{k} + \sigma_{k}}. \end{split}$$

Similarly, we have

$$\begin{split} \left| \rho_k^{(k)} - g_k^{(k)} \right| &\leq \frac{\Delta t^{\alpha_{k+\sigma_k} - 2} (1 - \alpha_{k+\sigma_k})}{T^{\alpha_{k+\sigma_k}}} \\ &\times \left\{ \int_{t_0}^{t_1} \left| t_{\frac{3}{2}} - \tau \right| \left| \left(\frac{t_{k+\sigma_k} - \tau}{T} \right)^{-\alpha_{k+\sigma_k}} - \sum_{i=\underline{N}+1}^{\overline{N}} \theta_i^{(k)} e^{\frac{-\lambda_i (t_{k+\sigma_k} - \tau)\Delta t}{T}} \right| \mathrm{d}\tau \right\} \\ &\leq \Delta t^{\alpha_{k+\sigma_k} - 2} (1 - \alpha_{k+\sigma_k}) \epsilon \int_{t_0}^{t_1} \left| t_{\frac{3}{2}} - \tau \right| (t_{k+\sigma_k} - \tau)^{-\alpha_{k+\sigma_k}} \mathrm{d}\tau \\ &= (1 - \alpha_{k+\sigma_k}) \epsilon \int_0^1 \left| \frac{3}{2} - \tau \right| (k + \sigma_k - \tau)^{-\alpha_{k+\sigma_k}} \mathrm{d}\tau \\ &\leq (1 - \alpha_{k+\sigma_k}) \Delta t^{-\alpha_{k+\sigma_k}} \epsilon \int_0^1 \left| \frac{3}{2} - \tau \right| \mathrm{d}\tau \\ &= \epsilon (1 - \alpha_{k+\sigma_k}) \Delta t^{-\alpha_{k+\sigma_k}}. \end{split}$$

The proof is complete.

209

Lemma 2.5. For $\alpha_{k+\sigma_k} \in (0,1)$, $\rho_l^{(k)}$ $(0 \le l \le k; 0 \le k \le n-1)$ are defined in (2.13) and (2.14) with $\sigma_k = 1 - \frac{\alpha_{k+\sigma_k}}{2}$ and a sufficiently small ϵ satisfying

$$\epsilon \le \frac{2(1-\overline{\alpha})(2-\frac{1}{2}\overline{\alpha})^{1-\overline{\alpha}}\Delta t^{\overline{\alpha}}}{(6-\frac{7}{2}\underline{\alpha})(1-\frac{1}{2}\underline{\alpha})}.$$

Then, we have

$$0 < \frac{(1-\epsilon)(1-\alpha_{k+\sigma_k})}{2(k+\sigma_k)^{\alpha_{k+\sigma_k}}} < \rho_k^{(k)} < \rho_{k-1}^{(k)} < \dots < \rho_0^{(k)},$$
(2.16)

$$(2\sigma_k - 1)\rho_0^{(k)} - \sigma_k \rho_1^{(k)} \ge 0.$$
(2.17)

Proof. For k = 0, $\rho_0^{(0)} = g_0^{(0)} > 0$ is obvious. For $k \ge 1$, from (2.14), the coefficients can be rewritten as

$$\begin{split} \rho_{l}^{(k)} &= \frac{\Delta t^{\alpha_{k+\sigma_{k}}}(1-\alpha_{k+\sigma_{k}})}{T^{\alpha_{k+\sigma_{k}}}} \\ &\times \begin{cases} \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} B_{i}^{(k)} + \Delta t^{-1} T^{\alpha_{k+\sigma_{k}}} \int_{t_{k}}^{t_{k+\sigma_{k}}} \frac{1}{(t_{k+\sigma_{k}}-\tau)^{\alpha_{k+\sigma_{k}}}} \mathrm{d}\tau, \quad l=0, \\ &\times \begin{cases} \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} \left(e^{\frac{-\lambda_{i}(l-1)\Delta t}{T}} A_{i}^{(k)} + e^{\frac{-\lambda_{i}l\Delta t}{T}} B_{i}^{(k)}\right), & 1 \leq l \leq k-1, \\ &\sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} e^{\frac{-\lambda_{i}(k-1)\Delta t}{T}} A_{i}^{(k)}, & l=k, \end{cases} \end{split}$$

where $A_i^{(k)}$ and $B_i^{(k)}$ are defined by (2.8). Thanks to $\theta_i^{(k)} > 0$, $\lambda_i > 0$ and the monotonicity of $e^{\tau \lambda_i \Delta t/T}$ with respect to τ , $A_i^{(k)} > 0$, $B_i^{(k)} > 0$ hold and then

$$0 < \rho_k^{(k)} < \rho_{k-1}^{(k)} < \rho_{k-2}^{(k)} < \dots < \rho_1^{(k)}.$$

According to $g_k^{(k)} \ge \frac{(1-\alpha_{k+\sigma_k})}{2(k+\sigma_k)^{\alpha_k+\sigma_k}}$ [11], (2.4),(2.6), and (2.14), we have

$$\rho_k^{(k)} \ge (1 - \epsilon) g_k^{(k)} \ge \frac{(1 - \epsilon)(1 - \alpha_{k+\sigma_k})}{2(k + \sigma_k)^{\alpha_{k+\sigma_k}}}$$

So condition (2.16) will hold if $\rho_0^{(k)} > \rho_1^{(k)}$ holds, an inequality which obviously follows from the condition (2.17). Thus it is enough to prove the latter one. By (2.15), the left-hand side of the condition (2.17) satisfies

$$(2\sigma_{k}-1)\rho_{0}^{(k)} - \sigma_{k}\rho_{1}^{(k)} \ge (2\sigma_{k}-1)g_{0}^{(k)} - \sigma_{k}g_{1}^{(k)} - (2\sigma_{k}-1)\frac{(1-\alpha_{k+\sigma_{k}})\epsilon}{4\Delta t^{\alpha_{k+\sigma_{k}}}} - \sigma_{k}\frac{(1-\alpha_{k+\sigma_{k}})\epsilon}{\Delta t^{\alpha_{k+\sigma_{k}}}}, \quad k = 1,$$
(2.18)

$$(2\sigma_{k}-1)\rho_{0}^{(k)} - \sigma_{k}\rho_{1}^{(k)} \ge (2\sigma_{k}-1)g_{0}^{(k)} - \sigma_{k}g_{1}^{(k)} - (2\sigma_{k}-1)\frac{(1-\alpha_{k+\sigma_{k}})\epsilon}{4\Delta t^{\alpha_{k+\sigma_{k}}}} - \sigma_{k}\frac{5(1-\alpha_{k+\sigma_{k}})\epsilon}{4\Delta t^{\alpha_{k+\sigma_{k}}}}, \quad k \ge 2.$$
(2.19)

From (2.4), the corresponding property about $g_l^{\left(k\right)}$ is

$$\begin{aligned} &(2\sigma_k - 1) g_0^{(k)} - \sigma_k g_1^{(k)} \\ &= \begin{cases} \frac{(2\sigma_k - 1)(1 - \sigma_k)}{2\sigma_k} (1 + \sigma_k)^{1 - \alpha_{k + \sigma_k}}, & k = 1, \\ (1 + \sigma_k)^{1 - \alpha_{k + \sigma_k}} \left(\frac{4\sigma_k - 1}{2\sigma_k} - \left(\frac{2 + \sigma_k}{1 + \sigma_k} \right)^{1 - \alpha_{k + \sigma_k}} \right), & k \ge 2, \end{cases} \\ &\geq \begin{cases} \frac{(2\sigma_k - 1)(1 - \sigma_k)}{2\sigma_k (1 + \sigma_k)^{\alpha_{k + \sigma_k}} - 1}, & k = 1, \\ \frac{(2\sigma_k - 1)(1 - \sigma_k)}{2\sigma_k (1 + \sigma_k)^{\alpha_{k + \sigma_k}}}, & k \ge 2, \end{cases} \\ &> 0. \end{aligned}$$

Thus in order to make the condition (2.17) hold, for k = 1, we just need

$$\frac{(2\sigma_k-1)(1-\sigma_k)}{2\sigma_k(1+\sigma_k)^{\alpha_k+\sigma_k}-1} - (2\sigma_k-1)\frac{(1-\alpha_{k+\sigma_k})\epsilon}{4\Delta t^{\alpha_{k+\sigma_k}}} - \sigma_k\frac{(1-\alpha_{k+\sigma_k})\epsilon}{\Delta t^{\alpha_{k+\sigma_k}}} \ge 0,$$

and for $k \geq 2$,

$$\frac{(2\sigma_k-1)(1-\sigma_k)}{2\sigma_k(1+\sigma_k)^{\alpha_k+\sigma_k}} - (2\sigma_k-1)\frac{(1-\alpha_{k+\sigma_k})\epsilon}{4\Delta t^{\alpha_{k+\sigma_k}}} - \sigma_k\frac{5(1-\alpha_{k+\sigma_k})\epsilon}{4\Delta t^{\alpha_{k+\sigma_k}}} \ge 0,$$

that is

$$\epsilon \leq \frac{2(2\sigma_k - 1)\Delta t^{\alpha_{k+\sigma_k}}}{\sigma_k(1 + \sigma_k)^{\alpha_{k+\sigma_k} - 1}} \min\left\{\frac{1}{6\sigma_k - 1}, \frac{1}{7\sigma_k - 1}\right\}.$$

In *FL*2-1 $_{\sigma}$ formula, $\sigma_k = 1 - \frac{\alpha_{k+\sigma_k}}{2}$. Thus we have

$$\epsilon \leq \frac{2(1-\alpha_{k+\sigma_k})\Delta t^{\alpha_{k+\sigma_k}}}{(6-\frac{7}{2}\alpha_{k+\sigma_k})(1-\frac{1}{2}\alpha_{k+\sigma_k})(2-\frac{1}{2}\alpha_{k+\sigma_k})^{\alpha_{k+\sigma_k}-1}}.$$

So we get (2.17) if this ϵ satisfies

$$\epsilon \leq \frac{2(1-\overline{\alpha})(2-\frac{1}{2}\overline{\alpha})^{1-\overline{\alpha}}\Delta t^{\overline{\alpha}}}{(6-\frac{7}{2}\underline{\alpha})(1-\frac{1}{2}\underline{\alpha})} \leq \frac{2(1-\alpha_{k+\sigma_{k}})\Delta t^{\alpha_{k+\sigma_{k}}}}{(6-\frac{7}{2}\alpha_{k+\sigma_{k}})(1-\frac{1}{2}\alpha_{k+\sigma_{k}})(2-\frac{1}{2}\alpha_{k+\sigma_{k}})^{\alpha_{k+\sigma_{k}}-1}}.$$

The proof is complete.

3. Difference schemes for the sub-diffusion problem

In this section, based on $FL2-1_{\sigma}$ formula in Section 2, we construct a fast temporal second-order and spatial fourth-order finite difference method ($FL2-1_{\sigma}$ scheme) for the VO time-fractional sub-diffusion equations. The unconditional stability and convergence of the difference method are investigated.

We consider the following multi-dimensional VO time-fractional sub-diffusion equations [11, 39], which is a promising approach to characterize time-dependent anomalous diffusion, or diffusion process in inhomogeneous porous media,

$${}_{0}^{C}\mathcal{D}_{t}^{\alpha(t)}u(\mathbf{x},t) = \Delta u(\mathbf{x},t) + f(\mathbf{x},t), \quad \mathbf{x} \in \Omega, \qquad t \in (0,T],$$
(3.1)

$$u(\mathbf{x},0) = \varphi(\mathbf{x}),$$
 $\mathbf{x} \in \overline{\Omega},$ (3.2)

$$u(\mathbf{x},t) = 0,$$
 $\mathbf{x} \in \partial\Omega, \quad t \in [0,T],$ (3.3)

where $\Omega = \prod_{p=1}^{d} (a_l^{(p)}, a_r^{(p)}) \subset \mathbb{R}^d$, $\partial \Omega$ is the boundary of Ω , $\overline{\Omega} = \Omega \cup \partial \Omega$, $\mathbf{x} = (x^{(1)}, x^{(2)}, \ldots, x^{(d)}) \in \Omega$, $\Delta u(\mathbf{x}, t) = \sum_{p=1}^{d} \partial_{x^{(p)}}^2 u(\mathbf{x}, t)$, $f(\mathbf{x}, t)$ and $\varphi(\mathbf{x})$ represent the given sufficiently smooth functions.

Denote $L^{(p)} = a_r^{(p)} - a_l^{(p)}$, p = 1, ..., d. Let $m^{(p)}$ be positive integers. Define a uniform partition of Ω by $x_{j^{(p)}}^{(p)} = a_l^{(p)} + j^{(p)}\Delta x^{(p)}$ $(j^{(p)} = 0, 1, ..., m^{(p)}; p = 1, ..., d)$ for $\Delta x^{(p)} = L^{(p)}/m^{(p)}$ and denote $\Delta x = \max_{1 \le p \le d} \Delta x^{(p)}$. Let

$$\Omega_{h} = \left\{ \left(x_{j^{(1)}}^{(1)}, x_{j^{(2)}}^{(2)}, \dots, x_{j^{(d)}}^{(d)} \right) \middle| j^{(p)} = 1, \dots, m^{(p)} - 1; p = 1, \dots, d \right\},
\overline{\Omega}_{h} = \left\{ \left(x_{j^{(1)}}^{(1)}, x_{j^{(2)}}^{(2)}, \dots, x_{j^{(d)}}^{(d)} \right) \middle| j^{(p)} = 0, 1, \dots, m^{(p)}; p = 1, \dots, d \right\},
\partial\Omega_{h} = \overline{\Omega}_{h} \setminus \Omega_{h}.$$

Let $j = (j^{(1)}, j^{(2)}, \dots, j^{(d)})$ and $\mathbf{x}_j = (x_{j^{(1)}}^{(1)}, x_{j^{(2)}}^{(2)}, \dots, x_{j^{(d)}}^{(d)})$, respectively denote the index vector and the spatial point. We define the index space $\overline{\mathcal{J}}$ by

$$\overline{\mathcal{J}} = \left\{ j | \mathbf{x}_j \in \overline{\Omega}_h \right\}, \quad \mathcal{J} = \left\{ j | \mathbf{x}_j \in \Omega_h \right\}, \quad \partial \mathcal{J} = \left\{ j | \mathbf{x}_j \in \partial \Omega_h \right\}.$$

Thus the grid function spaces are defined by

(...)

$$\mathcal{U} = \left\{ u | u \text{ being a grid function on } \overline{\Omega}_h \right\},$$
$$\mathcal{U} = \left\{ u | u \in \mathcal{U}; u_j = 0 \text{ when } j \in \partial \mathcal{J} \right\}.$$

We introduce the following discrete operators in the grid space \mathcal{U} :

$$\delta_{p} u_{j+\frac{1}{2}\delta_{p}} = \frac{1}{\Delta x^{(p)}} (u_{j+\delta_{p}} - u_{j}),$$

$$\delta_{p}^{2} u_{j} = \frac{1}{(\Delta x^{(p)})^{2}} (u_{j+\delta_{p}} - 2u_{j} + u_{j-\delta_{p}}),$$

$$\Delta_{h} u_{j} = \sum_{p=1}^{d} \delta_{p}^{2} u_{j},$$

where $\delta_p = (0, \dots, 1, \dots, 0)$ is an index with 1 at the *p*-th position and 0 at other positions. In order to construct the spatial fourth-order difference scheme, we introduce the average operator

$$\mathcal{A}_p u_j = \begin{cases} \frac{1}{12} (u_{j-\delta_p} + 10u_j + u_{j+\delta_p}), & j \in \mathcal{J}, \\ u_j, & j \in \partial \mathcal{J} \end{cases}$$

For any $u \in \overset{\circ}{\mathcal{U}}$, denote

$$\mathcal{A}_h u_j = \prod_{p=1}^d \mathcal{A}_p u_j, \quad \Lambda_h u_j = \sum_{p=1}^d \prod_{l=1, l \neq p}^d \mathcal{A}_l \delta_p^2 u_j.$$
(3.4)

In the grid function space $\mathring{\mathcal{U}}$, define the discrete inner products and norms

$$\begin{split} (u,w) &= \left(\prod_{r=1}^{d} \Delta x^{(r)}\right) \sum_{j \in \mathcal{J}} u_{j} w_{j}, \quad \|u\| = \sqrt{(u,u)}, \\ (u,w)_{\mathcal{A}_{h}} &= (\mathcal{A}_{h} u, w), \qquad \|u\|_{\mathcal{A}_{h}} = \sqrt{(u,\mathcal{A}_{h} u)}, \\ (\delta_{p} u, \delta_{p} w) &= \left(\prod_{r=1}^{d} \Delta x^{(r)}\right) \sum_{j^{(p)}=0}^{m^{(p)}-1} \left(\prod_{l=1, l \neq p}^{d} \sum_{j^{(l)}=1}^{m^{(l)}-1}\right) (\delta_{p} u_{j+\frac{1}{2}\delta_{p}}) (\delta_{p} w_{j+\frac{1}{2}\delta_{p}}), \\ |u|_{1,p} &= \sqrt{(\delta_{p} u, \delta_{p} u)}, \quad |u|_{1} = \sqrt{\sum_{r=1}^{d} |u|_{1,r}^{2}}, \\ (\delta_{p}^{2} u, \delta_{p}^{2} w) &= \left(\prod_{r=1}^{d} \Delta x^{(r)}\right) \sum_{j \in \mathcal{J}} (\delta_{p}^{2} u_{j}) \left(\delta_{p}^{2} w_{j}\right), \\ |u|_{2,p} &= \sqrt{(\delta_{p}^{2} u, \delta_{p}^{2} u)}, \quad \|u\|_{\infty} = \max_{j \in \mathcal{J}} |u_{j}|. \end{split}$$

3.1. FL2-1 $_{\sigma}$ scheme

Before deriving the finite difference schemes for the problem (3.1)-(3.3), we denote the numerical solution at time t_k with spatial point \mathbf{x}_j by u_j^k , and $f(\mathbf{x}_j, t_{k+\sigma_k})$ by $f_j^{k+\sigma_k}$ for $\mathbf{x}_j \in \overline{\Omega}_h$ and $0 \le k \le n$. We assume that the solution $u \in C^{(6,3)}(\overline{\Omega} \times [0,T])$.

Next we recall $L_{2-1_{\sigma}}$ scheme for the problem (3.1)-(3.3). Considering Eq. (3.1) at $(\mathbf{x}_j, t_{k+\sigma_k})$, we have

$${}_{0}^{C}\mathcal{D}_{t}^{\alpha(t)}u(\mathbf{x}_{j},t)|_{t=t_{k+\sigma_{k}}} = \Delta u(\mathbf{x}_{j},t_{k+\sigma_{k}}) + f_{j}^{k+\sigma_{k}}, \quad j \in \mathcal{J}, \quad 0 \le k \le n-1.$$
(3.5)

By Lemma 2.3, the term on the left-hand side of (3.5) satisfies

$$\sum_{0}^{C} \mathcal{D}_{t}^{\alpha(t)} u(\mathbf{x}_{j}, t)|_{t=t_{k+\sigma_{k}}}$$

$$= \sum_{0}^{FH} \mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}} u(\mathbf{x}_{j}, t_{k+\sigma_{k}}) + \mathcal{O}(\Delta t^{3-\alpha_{k+\sigma_{k}}} + \epsilon), \quad j \in \mathcal{J}, \quad 0 \le k \le n-1.$$

$$(3.6)$$

J.-L. Zhang, Z.-W. Fang and H.-W. Sun

On the other hand, using [11, Lemmas 3.4 and 3.5], the first term on the right-hand side of (3.5) satisfies

$$\Delta u(\mathbf{x}_j, t_{k+\sigma_k}) = \sigma_k \Delta u(\mathbf{x}_j, t_{k+1}) + (1 - \sigma_k) \Delta u(\mathbf{x}_j, t_k) + \mathcal{O}(\Delta t^2), \quad j \in \mathcal{J}.$$
(3.7)

Then substituting (3.6) and (3.7) into (3.5) gives

$$F_{0}^{H}\mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}}u(\mathbf{x}_{j}, t_{k+\sigma_{k}})$$

$$= \sigma_{k}\Delta u(\mathbf{x}_{j}, t_{k+1}) + (1 - \sigma_{k})\Delta u(\mathbf{x}_{j}, t_{k})$$

$$+ f_{j}^{k+\sigma_{k}} + \mathcal{O}(\Delta t^{2} + \epsilon), \quad j \in \overline{\mathcal{J}}, \quad 0 \le k \le n - 1.$$

Applying the averaging operator A_h in (3.4) to the above equation, we obtain

$$\mathcal{A}_{h} {}^{F_{0}} \mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}} u(\mathbf{x}_{j}, t_{k+\sigma_{k}})$$

= $\sigma_{k} \mathcal{A}_{h} \Delta u(\mathbf{x}_{j}, t_{k+1}) + (1 - \sigma_{k}) \mathcal{A}_{h} \Delta u(\mathbf{x}_{j}, t_{k})$
+ $\mathcal{A}_{h} f_{j}^{k+\sigma_{k}} + \mathcal{O}(\Delta t^{2} + \epsilon), \quad j \in \mathcal{J}, \quad 0 \le k \le n - 1,$

where

$$= \frac{T^{-\alpha_{k+\sigma_{k}}}}{\Gamma(1-\alpha_{k+\sigma_{k}})} \sum_{i=\underline{N}+1}^{\overline{N}} \theta_{i}^{(k)} H_{i}^{(j,k)} + s^{(k)} \sigma_{k}^{1-\alpha_{k+\sigma_{k}}} \left(u(\mathbf{x}_{j}, t_{k+1}) - u(\mathbf{x}_{j}, t_{k}) \right)$$

with

$$H_{i}^{(j,k)} = e^{\frac{-\lambda_{i}(1+\sigma_{k}-\sigma_{k-1})\Delta t}{T}} H_{i}^{(j,k-1)} + A_{i}^{(k)} (u(\mathbf{x}_{j}, t_{k}) - u(\mathbf{x}_{j}, t_{k-1})) + B_{i}^{(k)} (u(\mathbf{x}_{j}, t_{k+1}) - u(\mathbf{x}_{j}, t_{k})).$$

From [11], we obtain

$$\mathcal{A}_h \Delta u(\mathbf{x}_j, t_k) = \Lambda_h u(\mathbf{x}_j, t_k) + \mathcal{O}(\Delta x^4), \quad j \in \mathcal{J}, \quad 0 \le k \le n,$$

thus

$$\mathcal{A}_{h} {}^{FH}_{0} \mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}} u(\mathbf{x}_{j}, t_{k+\sigma_{k}})$$

$$= \Lambda_{h} \left(\sigma_{k} u(\mathbf{x}_{j}, t_{k+1}) + (1 - \sigma_{k}) u(\mathbf{x}_{j}, t_{k}) \right)$$

$$+ \mathcal{A}_{h} f_{j}^{k+\sigma_{k}} + S_{j}^{k}, \quad j \in \mathcal{J}, \quad 0 \le k \le n-1,$$
(3.8)

where there exists a constant c_0 such that

$$|S_j^k| \le c_0 \left(\Delta t^2 + \Delta x^4 + \epsilon\right), \quad j \in \mathcal{J}, \quad 0 \le k \le n - 1.$$
(3.9)

From the initial and boundary value conditions (3.2)-(3.3), we have

$$u(\mathbf{x}_j, 0) = \varphi(\mathbf{x}_j), \quad j \in \mathcal{J},$$
(3.10)

$$u(\mathbf{x}_j, t_k) = 0, \qquad j \in \partial \mathcal{J}, \quad 0 \le k \le n.$$
 (3.11)

Omitting the small term S_i^k in (3.8), we construct $FL_{2-1_{\sigma}}$ scheme for the problem (3.1)-(3.3) as follows:

$$\mathcal{A}_{h} \stackrel{FH}{}_{0} \mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}} u_{j}^{k+\sigma_{k}}$$

$$= \Lambda_{h} \left(\sigma_{k} u_{j}^{k+1} + (1-\sigma_{k}) u_{j}^{k} \right) + \mathcal{A}_{h} f_{j}^{k+\sigma_{k}}, \quad j \in \mathcal{J}, \quad 0 \le k \le n-1, \quad (3.12)$$

$$u_{j}^{0} = \varphi(\mathbf{x}_{j}), \quad j \in \mathcal{J} \quad (3.13)$$

$$u_j^0 = \varphi(\mathbf{x}_j), \quad j \in \mathcal{J},$$
(3.13)

$$u_j^k = 0, \qquad j \in \partial \mathcal{J}, \quad 0 \le k \le n,$$
(3.14)

where

$${}^{FH}_{0}\mathcal{D}^{\alpha_{k+\sigma_{k}}}_{t}u^{k+\sigma_{k}}_{j} = \frac{T^{-\alpha_{k+\sigma_{k}}}}{\Gamma(1-\alpha_{k+\sigma_{k}})}\sum_{i=\underline{N}+1}^{\overline{N}}\theta^{(k)}_{i}H^{(j,k)}_{i} + s^{(k)}\sigma^{1-\alpha_{k+\sigma_{k}}}_{k}\left(u^{k+1}_{j}-u^{k}_{j}\right)$$

with

$$H_i^{(j,k)} = e^{\frac{-\lambda_i(1+\sigma_k-\sigma_{k-1})\Delta t}{T}} H_i^{(j,k-1)} + A_i^{(k)} \left(u_j^k - u_j^{k-1} \right) + B_i^{(k)} \left(u_j^{k+1} - u_j^k \right).$$

Recall L2-1 $_{\sigma}$ scheme for the problem (3.1)-(3.3) as follows [11]:

$$\mathcal{A}_{h} {}^{H}_{0} \mathcal{D}^{\alpha_{k+\sigma_{k}}}_{t} u^{k+\sigma_{k}}_{j}$$

$$= \Lambda_{h} \left(\sigma_{k} u^{k+1}_{j} + (1-\sigma_{k}) u^{k}_{j} \right) + \mathcal{A}_{h} f^{k+\sigma_{k}}_{j}, \quad j \in \mathcal{J}, \quad 0 \le k \le n-1,$$
(3.15)

$$u_j^0 = \varphi(\mathbf{x}_j), \quad j \in \mathcal{J},$$
(3.16)

$$u_j^k = 0, \qquad j \in \partial \mathcal{J}, \quad 0 \le k \le n,$$
(3.17)

where

$${}^{H}_{0}\mathcal{D}^{\alpha_{k+\sigma_{k}}}_{t}u^{k+\sigma_{k}}_{j} = s^{(k)}\sum_{l=0}^{k}g^{(k)}_{l}\left(u^{k-l+1}_{j} - u^{k-l}_{j}\right).$$

3.2. Stability and convergence of $FL2-1_{\sigma}$ scheme

As described in Lemma 2.5, the coefficients $\rho_l^{(k)}$ hold the vital properties for the stability and convergence analysis. Thus, similar to the proof given in [11], we present the following lemmas which will be used in the analysis of FL2-1 $_{\sigma}$ scheme (3.12)-(3.14).

Lemma 3.1 ([1]). Let $\mathring{\mathcal{U}}$ be an inner product space and $\langle \cdot, \cdot \rangle_*$ is the inner product with the induced norm $\|\cdot\|_*$. Suppose $\{c_l^{(k)}|0 \leq l \leq k, k \geq 1\}$ satisfies $0 < c_k^{(k)} < c_{k-1}^{(k)} < \cdots < c_0^{(k)}$. For $v^0, v^1, \ldots, v^{k+1} \in \mathring{\mathcal{U}}$, we have the following inequality:

$$\sum_{l=0}^{k} c_{l}^{(k)} \left\langle v^{k-l+1} - v^{k-l}, \sigma_{k} v^{k+1} + (1 - \sigma_{k}) v^{k} \right\rangle_{*}$$
$$\geq \frac{1}{2} \sum_{l=0}^{k} c_{l}^{(k)} \left(\|v^{k-l+1}\|_{*}^{2} - \|v^{k-l}\|_{*}^{2} \right).$$

J.-L. Zhang, Z.-W. Fang and H.-W. Sun

Lemma 3.2 ([11]). For any $u, w \in \mathcal{U}$, define

$$\langle u, w \rangle_{\mathcal{A}_h} = (\mathcal{A}_h u, -\Delta_h w).$$

Then $\langle u,w\rangle_{\mathcal{A}_h}$ is an inner product on $\mathring{\mathcal{U}}.$ We denote

$$|u|_{1,\mathcal{A}_h} = \sqrt{\langle u, u \rangle_{\mathcal{A}_h}}.$$

Lemma 3.3 ([11]). For any $u \in \mathring{\mathcal{U}}$, we have

$$\left(\frac{2}{3}\right)^d |u|_1^2 \le |u|_{1,\mathcal{A}_h}^2 \le |u|_1^2.$$

Lemma 3.4 ([11]). For any $u \in \mathcal{U}$, we have

$$\left(\frac{2}{3}\right)^{d-1} \|\Delta_h u\|^2 \le \left(\Lambda_h u, \Delta_h u\right) \le \|\Delta_h u\|^2.$$

Now we obtain the following theorem to state the unconditional stability of the proposed scheme.

Theorem 3.1. Let $\{u_j^k | j \in \overline{\mathcal{J}}, 0 \le k \le n\}$ be the solution of the difference scheme (3.12)-(3.14). Then, we have

$$|u^{k}|_{1,\mathcal{A}_{h}}^{2} \leq |u^{0}|_{1,\mathcal{A}_{h}}^{2} + \left(\frac{3}{2}\right)^{d-1} \frac{1}{1-\epsilon} c_{1} \max_{0 \leq l \leq k-1} \|\mathcal{A}_{h}f^{l+\sigma_{l}}\|^{2}, \quad 0 \leq k \leq n,$$
(3.18)

where

$$\|\mathcal{A}_h f^{l+\sigma_l}\|^2 = \left(\prod_{r=1}^d \Delta x^{(r)}\right) \sum_{j \in \mathcal{J}} \left(\mathcal{A}_h f_j^{l+\sigma_l}\right)^2, \quad c_1 = \max_{0 \le t \le T} \left\{ t^{\alpha(t)} \Gamma\left(1-\alpha(t)\right) \right\}.$$

Proof. Denote $u^{k+\sigma_k} = \sigma_k u^{k+1} + (1 - \sigma_k) u^k$. Making an inner product with $-\Delta_h u^{k+\sigma_k}$ on both hand sides of (3.12), we obtain

$$\left(\mathcal{A}_{h} {}^{FH}_{0} \mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}} u^{k+\sigma_{k}}, -\Delta_{h} u^{k+\sigma_{k}} \right) + \left(\Lambda_{h} u^{k+\sigma_{k}}, \Delta_{h} u^{k+\sigma_{k}} \right)$$

$$= - \left(\mathcal{A}_{h} f^{k+\sigma_{k}}, \Delta_{h} u^{k+\sigma_{k}} \right), \quad 0 \le k \le n-1.$$

$$(3.19)$$

Noticing (3.14), (2.12) and Lemmas 2.5-3.2, we get

$$\sum_{l=0}^{k} \rho_{l}^{(k)} \left\langle u^{k-l+1} - u^{k-l}, \sigma_{k} u^{k+1} + (1 - \sigma_{k}) u^{k} \right\rangle_{\mathcal{A}_{h}}$$
$$\geq \frac{1}{2} \sum_{l=0}^{k} \rho_{l}^{(k)} \left(|u^{k-l+1}|_{1,\mathcal{A}_{h}}^{2} - |u^{k-l}|_{1,\mathcal{A}_{h}}^{2} \right).$$

By Lemma 3.4, the second term on the left-hand side of (3.19) follows that

$$\left(\Lambda_h u^{k+\sigma_k}, \Delta_h u^{k+\sigma_k}\right) \ge \left(\frac{2}{3}\right)^{d-1} \|\Delta_h u^{k+\sigma_k}\|^2.$$

Substituting the two inequalities into (3.19) and using the Cauchy-Schwarz inequality with the basic inequality

$$ab \le \left(\frac{2}{3}\right)^{d-1} a^2 + \left(\frac{3}{2}\right)^{d-1} \frac{1}{4} b^2,$$

we have

$$\frac{s^{(k)}}{2} \sum_{l=0}^{k} \rho_{l}^{(k)} \left(|u^{k-l+1}|_{1,\mathcal{A}_{h}}^{2} - |u^{k-l}|_{1,\mathcal{A}_{h}}^{2} \right) + \left(\frac{2}{3}\right)^{d-1} \|\Delta_{h} u^{k+\sigma_{k}}\|^{2} \\
\leq -\left(\mathcal{A}_{h} f^{k+\sigma_{k}}, \Delta u^{k+\sigma_{k}}\right) \leq \|\mathcal{A}_{h} f^{k+\sigma_{k}}\| \|\Delta u^{k+\sigma_{k}}\| \\
\leq \left(\frac{2}{3}\right)^{d-1} \|\Delta u^{k+\sigma_{k}}\|^{2} + \left(\frac{3}{2}\right)^{d-1} \frac{1}{4} \|\mathcal{A}_{h} f^{k+\sigma_{k}}\|^{2}, \quad 0 \leq k \leq n-1,$$

which follows that

$$\frac{s^{(k)}}{2} \sum_{l=0}^{k} \rho_l^{(k)} \left(|u^{k-l+1}|_{1,\mathcal{A}_h}^2 - |u^{k-l}|_{1,\mathcal{A}_h}^2 \right)$$

$$\leq \left(\frac{3}{2}\right)^{d-1} \frac{1}{4} \|\mathcal{A}_h f^{k+\sigma_k}\|^2, \quad 0 \leq k \leq n-1.$$

Further we get

$$\rho_{0}^{(k)}|u^{k+1}|_{1,\mathcal{A}_{h}}^{2} \leq \sum_{l=0}^{k-1} \left(\rho_{l}^{(k)} - \rho_{l+1}^{(k)}\right)|u^{k-l}|_{1,\mathcal{A}_{h}}^{2} + \rho_{k}^{(k)}|u^{0}|_{1,\mathcal{A}_{h}}^{2} + \left(\frac{3}{2}\right)^{d-1} \frac{1}{2s^{(k)}} \|\mathcal{A}_{h}f^{k+\sigma_{k}}\|^{2}, \quad 0 \leq k \leq n-1.$$

According to Lemma 2.5, it follows that

$$\frac{1}{2s^{(k)}\rho_k^{(k)}} < \frac{1}{1-\epsilon} \frac{(k+\sigma_k)^{\alpha_k+\sigma_k}}{s^{(k)}(1-\alpha_{k+\sigma_k})} = \frac{1}{1-\epsilon} t^{\alpha(t)} \Gamma(1-\alpha(t))|_{t=t_{k+\sigma_k}} \le \frac{1}{1-\epsilon} c_1,$$

which leads to

$$\rho_{0}^{(k)}|u^{k+1}|_{1,\mathcal{A}_{h}}^{2} \leq \sum_{l=0}^{k-1} \left(\rho_{l}^{(k)} - \rho_{l+1}^{(k)}\right)|u^{k-l}|_{1,\mathcal{A}_{h}}^{2}$$

$$+ \rho_{k}^{(k)} \left(|u^{0}|_{1,\mathcal{A}_{h}}^{2} + \left(\frac{3}{2}\right)^{d-1} \frac{1}{1-\epsilon} c_{1} \|\mathcal{A}_{h}f^{k+\sigma_{k}}\|^{2}\right), \quad 0 \leq k \leq n-1.$$

$$(3.20)$$

Next the mathematical induction will be used to prove the inequality (3.18). It is valid for k = 0. Assume (3.18) is true for $0 \le k \le q$, now we prove that (3.18) is valid for k = q + 1. From (3.20), we obtain

$$\begin{split} &\rho_0^q |u^{q+1}|_{1,\mathcal{A}_h}^2 \\ &\leq \sum_{l=0}^{q-1} \left(\rho_l^{(q)} - \rho_{l+1}^{(q)} \right) |u^{q-l}|_{1,\mathcal{A}_h}^2 + \rho_q^{(q)} \left(|u^0|_{1,\mathcal{A}_h}^2 + \left(\frac{3}{2}\right)^{d-1} \frac{1}{1-\epsilon} c_1 \|\mathcal{A}_h f^{q+\sigma_q}\|^2 \right) \\ &\leq \sum_{l=0}^{q-1} \left(\rho_l^{(q)} - \rho_{l+1}^{(q)} \right) \left(|u^0|_{1,\mathcal{A}_h}^2 + \left(\frac{3}{2}\right)^{d-1} \frac{1}{1-\epsilon} c_1 \max_{0 \le s \le q-l-1} \|\mathcal{A}_h f^{s+\sigma_s}\|^2 \right) \\ &+ \rho_q^{(q)} \left(|u^0|_{1,\mathcal{A}_h}^2 + \left(\frac{3}{2}\right)^{d-1} \frac{1}{1-\epsilon} c_1 \|\mathcal{A}_h f^{q+\sigma_q}\|^2 \right) \\ &\leq \left(\sum_{l=0}^{q-1} (\rho_l^{(q)} - \rho_{l+1}^{(q)}) + \rho_q^{(q)} \right) \left(|u^0|_{1,\mathcal{A}_h}^2 + \left(\frac{3}{2}\right)^{d-1} \frac{1}{1-\epsilon} c_1 \max_{0 \le s \le q} \|\mathcal{A}_h f^{s+\sigma_s}\|^2 \right) \\ &\leq \rho_0^{(q)} \left(|u^0|_{1,\mathcal{A}_h}^2 + \left(\frac{3}{2}\right)^{d-1} \frac{1}{1-\epsilon} c_1 \max_{0 \le s \le q} \|\mathcal{A}_h f^{s+\sigma_s}\|^2 \right). \end{split}$$

From the above inequality, we obtain

$$|u^{q+1}|_{1,\mathcal{A}_h}^2 \le |u^0|_{1,\mathcal{A}_h}^2 + \left(\frac{3}{2}\right)^{d-1} \frac{1}{1-\epsilon} c_1 \max_{0 \le s \le q} \|\mathcal{A}_h f^{s+\sigma_s}\|^2.$$

Therefore, inequality (3.18) is valid for k = q + 1. This completes the proof.

Theorem 3.1 reveals the stability of the difference scheme (3.12)-(3.14) with respect to the initial value and the source term. The next theorem is about the convergence of FL2-1 $_{\sigma}$ scheme.

Theorem 3.2. Let $u(\mathbf{x},t) \in C^{(6,3)}(\overline{\Omega} \times [0,T])$ be the exact solution of the problem (3.1)-(3.3), and $\{u_j^k | j \in \overline{\mathcal{J}}, 0 \le k \le n\}$ be the solution of the difference scheme (3.12)-(3.14). Denote $e_j^k = u(\mathbf{x}_j, t_k) - u_j^k$. Then, we have

$$|e^k|_{1,\mathcal{A}_h} \leq \sqrt{\left(\frac{3}{2}\right)^{d-1} \frac{1}{1-\epsilon} c_1 \prod_{r=1}^d L^{(r)} c_0 \left(\Delta t^2 + \Delta x^4 + \epsilon\right)}, \quad 0 \leq k \leq n.$$

Furthermore, we obtain

$$|e^{k}|_{1} \leq \sqrt{\left(\frac{3}{2}\right)^{2d-1} \frac{1}{1-\epsilon} c_{1} \prod_{r=1}^{d} L^{(r)} c_{0} \left(\Delta t^{2} + \Delta x^{4} + \epsilon\right), \quad 0 \leq k \leq n.$$

Proof. Subtracting (3.12)-(3.14) from (3.8), (3.10)-(3.11), respectively, we obtain the error equations as follows:

$$\begin{aligned} \mathcal{A}_{h} \stackrel{FH}{}_{0} \mathcal{D}_{t}^{\alpha_{k+\sigma_{k}}} e_{j}^{k} &= \Lambda_{h} \left(\sigma_{k} e_{j}^{k+1} + (1-\sigma_{k}) e_{j}^{k} \right) + S_{j}^{k}, \ j \in \mathcal{J}, \ 0 \leq k \leq n-1, \\ e_{j}^{0} &= 0, \ j \in \mathcal{J}, \\ e_{j}^{k} &= 0, \ j \in \partial \mathcal{J}, \ 0 \leq k \leq n. \end{aligned}$$

Applying (3.9) and the priori estimation (3.18), it leads to

$$|e^{k}|_{1,\mathcal{A}_{h}}^{2} \leq |e^{0}|_{1,\mathcal{A}_{h}}^{2} + \left(\frac{3}{2}\right)^{d-1} \frac{1}{1-\epsilon} c_{1} \max_{0 \leq l \leq k-1} \|S^{l}\|^{2}$$
$$\leq \left(\frac{3}{2}\right)^{d-1} \frac{1}{1-\epsilon} c_{1} \prod_{r=1}^{d} L^{(r)} \left(c_{0} \left(\Delta t^{2} + \Delta x^{4} + \epsilon\right)\right)^{2}, \quad 0 \leq k \leq n.$$

Consequently, we have

$$|e^k|_{1,\mathcal{A}_h} \leq \sqrt{\left(\frac{3}{2}\right)^{d-1} \frac{1}{1-\epsilon} c_1 \prod_{r=1}^d L^{(r)} c_0 \left(\Delta t^2 + \Delta x^4 + \epsilon\right)}, \quad 0 \leq k \leq n.$$

Furthermore, from Lemma 3.3, we obtain

$$|e^{k}|_{1} \leq \sqrt{\left(\frac{3}{2}\right)^{d}} |e^{k}|_{1,\mathcal{A}_{h}} \leq \sqrt{\left(\frac{3}{2}\right)^{2d-1} \frac{1}{1-\epsilon} c_{1} \prod_{r=1}^{d} L^{(r)} c_{0} \left(\Delta t^{2} + \Delta x^{4} + \epsilon\right)}, \quad 0 \leq k \leq n.$$

The proof is complete.

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4. Numerical results

In this section, some numerical examples are presented to verify the effectiveness of $FL2-1_{\sigma}$ scheme (3.12)-(3.14) compared with $L2-1_{\sigma}$ scheme (3.15)-(3.17). Besides, $FL_{2-1_{\sigma}}$ scheme is extended to the graded mesh to test the problem with a non-smooth solution. All experiments are performed based on Matlab 2016b on a laptop with the configuration: Intel(R) Core(TM) i7-7500U CPU 2.70GHz and 8.00 GB RAM.

Example 4.1. We show the efficiency of $FL_{2-1_{\sigma}}$ scheme (3.12)-(3.14) in 2D case comparing with the corresponding $L2-1_{\sigma}$ scheme (3.15)-(3.17). Take $\Omega = (0,\pi) \times (0,\pi)$, T = 1, and the exact solution is given as [11]

$$u(\mathbf{x},t) = (t^3 + 3t^2 + 1)\sin x^{(1)}\sin x^{(2)}$$

Based on the exact solution, we calculate the initial value and the source term

(2)

$$\varphi(\mathbf{x}) = \sin x^{(1)} \sin x^{(2)},$$

$$f(\mathbf{x}, t) = \left(\frac{6t^{3-\alpha(t)}}{\Gamma(4-\alpha(t))} + \frac{6t^{2-\alpha(t)}}{\Gamma(3-\alpha(t))} + 2\left(t^3 + 3t^2 + 1\right)\right) \sin x^{(1)} \sin x^{(2)}.$$

We take $\Delta x^{(1)} = \Delta x^{(2)} = \Delta x$, $m^{(1)} = m^{(2)} = m$, denote

$$E(m,n) = \left\| u^n - u(\mathbf{x},t_n) \right\|_{\infty},$$

$$Order_t = \log_2\left(\frac{E(m,2n)}{E(m,n)}\right),$$

$$Order_{x,t} = \log_2\left(\frac{E(2m,2n)}{E(m,n)}\right).$$

In the calculations, we set the expected accuracy $\epsilon = \Delta t^2$ and different spatial and temporal step sizes. Note that the linear systems arising from the two-dimensional problems provide coefficient matrices possessing block-tridiagonal-Toeplitz with tridiagonal-Toeplitz-blocks, which can be diagonalized by the discrete sine transforms [6, 34]. Therefore, as a global after-processing optimization, a fast implementation of the inversion, in our numerical experiments, is carried out by the fast sine transforms to reduce the computational cost.

Tables 1 and 2 list the results of Example 4.1. Fine spatial size is fixed at $\Delta x = \pi/320$ in Table 1. Both $L2\text{-}1_{\sigma}$ scheme and $FL2\text{-}1_{\sigma}$ scheme can achieve the second-order temporal accuracy. Table 1 also shows the developments of the CPU time and memory of the two schemes with respect to n. The CPU time of $FL2\text{-}1_{\sigma}$ scheme is increasing half as fast as that of $L2\text{-}1_{\sigma}$ scheme, which reveals the $\mathcal{O}(n \log^2 n)$ and $\mathcal{O}(n^2)$ computational complexity of the two schemes, respectively. We note that as n goes up, the memory of $FL2\text{-}1_{\sigma}$ scheme grows slowly, while the storage requirement of $L2\text{-}1_{\sigma}$ scheme increases linearly with n. Especially, when n = 16000, $FL2\text{-}1_{\sigma}$ scheme is finished in 40 min,

Table 1: Convergence rates and the CPU time, memory of $L2-1_{\sigma}$ scheme and $FL2-1_{\sigma}$ scheme for Example 4.1 with $\alpha(t) = (2 + \sin t)/4$, m = 320, $\epsilon = \Delta t^2$.

n		$L2-1_{\sigma}$ s	scheme		$FL2-1_{\sigma}$ scheme				
16	E(m,n)	$Order_t$	CPU(s)	Memory	E(m,n)	$Order_t$	CPU(s)	Memory	
2000	2.3592e-7	-	152.77	1.64e+9	2.3497e-7	-	194.70	1.01e+8	
4000	5.8588e-8	2.01	642.33	3.27e+9	5.8411e-8	2.01	470.72	1.17e+8	
8000	1.4339e-8	2.03	2510.36	6.52e+9	1.4319e-8	2.03	1021.68	1.34e+8	
16000	-	-	-	-	3.3034e-9	2.12	2311.46	1.53e+8	

Table 2: Convergence rates and the CPU time, memory of $L2-1_{\sigma}$ scheme and $FL2-1_{\sigma}$ scheme for Example 4.1 with $\alpha(t) = (2 + \sin t)/4$, $n = m^2$, $\epsilon = \Delta t^2$.

m		$L2-1_{\sigma}$ sc	heme		$FL2$ -1 $_{\sigma}$ scheme				
111	E(m,n)	$Order_{x,t}$	CPU(s)	Memory	E(m,n)	$Order_{x,t}$	CPU(s)	Memory	
20	1.1392e-6	-	0.15	1.20e+6	1.1971e-6	-	0.14	2.56e+5	
40	7.2797e-8	3.97	3.23	1.96e+7	7.4374e-8	4.01	2.05	1.48e+6	
80	4.6192e-9	3.98	185.32	3.20e+8	4.6405e-9	4.00	52.46	7.95e+6	
160	2.4931e-10	4.21	7158.69	5.18e+9	2.4589e-10	4.24	1073.38	4.15e+7	

while $L2 \cdot 1_{\sigma}$ scheme is failed due to excessive storage requirements. Table 2 gives the numerical results with m varying from 20 to 160 and $n = m^2$. The convergence rates satisfy the theoretical result in Section 3. Nevertheless, a significant reduction is reflected in computational cost and storage memory of $FL2 \cdot 1_{\sigma}$ scheme on the refined mesh, compared with $L2 \cdot 1_{\sigma}$ scheme.

Example 4.2. We also show the efficiency of FL2-1 $_{\sigma}$ scheme (3.12)-(3.14) in 3D case. Take $\Omega = (0, \pi) \times (0, \pi) \times (0, \pi)$, T = 1, and the exact solution is given as

$$u(\mathbf{x},t) = (t^3 + 3t^2 + 1)\sin x^{(1)}\sin x^{(2)}\sin x^{(3)}.$$

Based on the exact solution, we calculate the initial value and the source term

$$\varphi(\mathbf{x}) = \sin x^{(1)} \sin x^{(2)} \sin x^{(3)},$$

$$f(\mathbf{x}, t) = \left(\frac{6t^{3-\alpha(t)}}{\Gamma(4-\alpha(t))} + \frac{6t^{2-\alpha(t)}}{\Gamma(3-\alpha(t))} + 3\left(t^3 + 3t^2 + 1\right)\right) \sin x^{(1)} \sin x^{(2)} \sin x^{(3)}.$$

We take $\Delta x^{(1)} = \Delta x^{(2)} = \Delta x^{(3)} = \Delta x$, $m^{(1)} = m^{(2)} = m^{(3)} = m$, and set the expected accuracy $\epsilon = \Delta t^2$. The errors and convergence orders, CPU time and storage of L2-1 $_{\sigma}$ scheme and FL2-1 $_{\sigma}$ scheme are shown in Table 3 with m = 100 and temporal step sizes refined from $\Delta t = \frac{1}{200}$ to $\Delta t = \frac{1}{1600}$, while in Table 4 m varies from 10 to 80 and $n = (2m)^2$. The fast sine transforms is used to reduce the computational cost.

Tables 3 and 4 show that both $FL2-1_{\sigma}$ scheme and $L2-1_{\sigma}$ scheme can achieve the optimal convergence for three-dimensional problems. Nevertheless, complexity

Table 3: Convergence rates and the CPU time, memory of L2- 1_{σ} scheme and FL2- 1_{σ} scheme for Example 4.2 with $\alpha(t) = (2 + \sin t)/4$, m = 100, $\epsilon = \Delta t^2$.

n		$L2-1_{\sigma}$ s	cheme		$FL2$ -1 $_{\sigma}$ scheme				
11	E(m,n)	$Order_t$	CPU(s)	Memory	E(m,n)	$Order_t$	CPU(s)	Memory	
200	2.6755e-5	-	41.64	1.64e+9	2.6587e-5	-	99.77	5.59e+8	
400	6.6637e-6	2.01	156.85	3.19e+9	6.6318e-6	2.00	233.83	6.6.e+8	
800	1.6528e-6	2.01	680.60	6.30e+9	1.6475e-6	2.01	564.19	7.84e+8	
1600	-	-	-	-	4.0177e-7	2.04	1358.80	9.24e+8	

Table 4: Convergence rates and the CPU time, memory of $L2-1_{\sigma}$ scheme and $FL2-1_{\sigma}$ scheme for Example 4.2 with $\alpha(t) = (2 + \sin t)/4$, $n = (2m)^2$, $\epsilon = \Delta t^2$.

m		$L2-1_{\sigma}$ s	cheme		$FL2$ -1 $_{\sigma}$ scheme				
111	E(m,n)	$Order_{x,t}$	CPU(s)	Memory	E(m,n)	$Order_{x,t}$	CPU(s)	Memory	
10	1.2679e-4	-	0.32	2.41e+6	1.2682e-4	-	0.52	5.06e+5	
20	7.9012e-6	4.00	13.54	8.84e+7	7.9021e-6	4.00	12.61	6.56e+6	
40	4.9351e-7	4.00	1047.68	3.04e+9	4.9351e-7	4.00	508.26	7.46e+7	
80	-	-	-	-	3.0832e-8	4.00	20550.89	8.01e+8	

of $FL2-1_{\sigma}$ scheme is much cheaper than that of $L2-1_{\sigma}$ scheme on the refined mesh. For the fine mesh, however, $L2-1_{\sigma}$ scheme has very low efficiency or even cannot proceed because of the limit of memory, while $FL2-1_{\sigma}$ scheme solves the relevant problem very well.

Example 4.3. An essential feature of the problem (3.1)-(3.3) is the weak singularity at the initial time. In order to capture the dramatic solution, we apply the fast scheme on the graded mesh [20, 26, 37]. Set $t_k = T(k/n)^r$ for k = 0, 1, ..., n, where the constant mesh grading $r \ge 1$ is chosen according to the singularity of the solution. Especially, the mesh is uniform if r = 1. Set $\Delta t_k = t_{k+1} - t_k$ and $t_{k+\sigma_k} = t_k + \sigma_k \Delta t_k$ for k = 0, 1, ..., n - 1. Similarly to (2.9), we have $FL2 \cdot 1_{\sigma}$ formula on the graded mesh as

with

$$\widehat{H}_{i}^{(j,k)} = e^{\frac{-\lambda_{i}(\Delta t_{k-1} - \sigma_{k-1}\Delta t_{k-1} + \sigma_{k}\Delta t_{k})}{T}} \widehat{H}_{i}^{(j,k-1)} + \widehat{A}_{i}^{(k)} \left(u_{j}^{k} - u_{j}^{k-1}\right) + \widehat{B}_{i}^{(k)} \left(u_{j}^{k+1} - u_{j}^{k}\right),$$

where $\widehat{H}_{i}^{(j,0)} = 0$ and

$$\hat{A}_{i}^{(k)} = \frac{2}{(\Delta t_{k} + \Delta t_{k-1})\Delta t_{k-1}} \int_{t_{k-1}}^{t_{k}} (t_{k+\frac{1}{2}} - \tau) e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}} - \tau)}{T}} \mathrm{d}\tau,$$
$$\hat{B}_{i}^{(k)} = \frac{2}{(\Delta t_{k} + \Delta t_{k-1})\Delta t_{k}} \int_{t_{k-1}}^{t_{k}} (\tau - t_{k-\frac{1}{2}}) e^{\frac{-\lambda_{i}(t_{k+\sigma_{k}} - \tau)}{T}} \mathrm{d}\tau.$$

Remark 4.1. The quadrature exponents λ_i and weights $\theta_i^{(k)}$ in the ESA technique are chosen by Lemma 2.2. All the other parameters remain the same as the uniform mesh, the only difference is that on the graded mesh we take

$$\overline{N} = \left\lfloor \frac{1}{h} \left(\log \frac{T}{\Delta t_1} + \log \log \epsilon^{-1} + \log \underline{\alpha} + 2^{-1} \right) \right\rfloor.$$

Now we have FL2-1 $_{\sigma}$ scheme on the graded mesh as follows

$$\mathcal{A}_{h} {}^{FH}_{0} \widehat{\mathcal{D}}_{t}^{\alpha_{k+\sigma_{k}}} u_{j}^{k+\sigma_{k}}$$
$$= \Lambda_{h} \left(\sigma_{k} u_{j}^{k+1} + (1-\sigma_{k}) u_{j}^{k} \right) + \mathcal{A}_{h} f_{j}^{k+\sigma_{k}}, \quad j \in \mathcal{J}, \qquad 0 \le k \le n-1,$$
(4.1)

$$u_j^0 = \varphi(\mathbf{x}_j), \qquad \qquad j \in \mathcal{J}, \tag{4.2}$$

$$u_j^k = 0,$$
 $j \in \partial \mathcal{J}, \quad 0 \le k \le n.$ (4.3)

We show the efficiency of the fast algorithm on the graded mesh comparing with the corresponding direct scheme. Take $\Omega = (0, \pi) \times (0, \pi)$, T = 1, the initial value $\varphi(\mathbf{x}) = 1$ and the source term $f(\mathbf{x}, t) = 1$. In the calculations, we use the numerical solutions \widehat{U} to the corresponding problem discretized with $m^{(1)} = m^{(2)} = m = 160$, n = 51200 as the reference solutions. Define the error and the convergence rate in time by

$$E(m,n) = \|u^n - \widehat{U}^n\|_{\infty}, \quad Order_t = \log_2\left(\frac{E(m,2n)}{E(m,n)}\right),$$

respectively.

To test the convergence rate in time, we take different n and set the expected accuracy $\epsilon = (1/n)^2$, while the spatial size is fixed at $m^{(1)} = m^{(2)} = m = 160$. Table 5 shows the errors and orders in the computed solutions for Example 4.3 with different values of the mesh grading exponent r. In the case of a uniform mesh (r = 1) we observe a first-order accuracy, while for a grading of $r = 2/\underline{\alpha}$, the optimal rate is obtained. FL2-1 $_{\sigma}$ scheme saves much memory and computational complexity than L2-1 $_{\sigma}$ scheme on the graded mesh. It certifies that the fast algorithm is valid on the graded mesh and can efficiently solve the problem even the solution has singularity at the initial time.

Table 5: Convergence rates and the CPU time, memory of $L2-1_{\sigma}$ scheme and $FL2-1_{\sigma}$ scheme on the graded mesh for Example 4.3 with $\alpha(t) = (2 + \sin t)/4$, m = 160, $\epsilon = (1/n)^2$.

	n	$L2-1_{\sigma}$ scheme					$FL2-1_{\sigma}$ scheme				
	\overline{n}	E(m,n)	$Order_t$	CPU(s)	Memory	E(m,n)	$Order_t$	CPU(s)	Memory		
	2000	9.1313e-6	-	61.98	4.08e+8	1.4450e-5	-	99.22	4.84e+7		
n — 1	4000	4.5713e-6	1.00	256.86	8.12e+8	7.2617e-6	0.99	235.02	5.65e+7		
7 — 1	8000	2.2877e-6	1.00	1011.09	1.62e+9	3.6445e-6	0.99	534.67	6.51e+7		
	16000	1.1440e-6	1.00	4099.87	3.24e+9	1.8273e-6	1.00	1235.64	7.42e+7		
	2000	3.7084e-8	-	63.37	4.08e+8	3.7725e-8	-	149.07	7.31e+7		
. 1	4000	9.2642e-9	2.00	242.00	8.12e+8	9.5153e-9	1.99	356.87	8.57e+7		
7 - 4	8000	2.2777e-9	2.02	1018.81	1.62e+9	2.3866e-9	2.00	814.74	9.87e+7		
	16000	5.4073e-10	2.07	4122.61	3.24e+9	5.8921e-10	2.02	1886.16	1.13e+8		

5. Concluding remarks

In this paper, we consider the fast high-order evaluation for the VO Caputo fractional derivative. $FL2-1_{\sigma}$ formula can efficiently reduce the computational storage and cost for the VO fractional derivative. The fast formula is applied to construct $FL2-1_{\sigma}$ scheme for the multi-dimensional VO fractional sub-diffusion equations. We show the properties of $FL2-1_{\sigma}$ scheme to study the stability and convergence. Numerical examples are given to verify the theoretical results. The fast algorithm is also tested on the graded mesh, which is efficient to solve the problem possessing weak singularity at the start of the solution.

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