# Preservation of Linear Constraints in Approximation of Tensors 

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#### Abstract

For an arbitrary tensor (multi-index array) with linear constraints at each direction, it is proved that the factors of any minimal canonical tensor approximation to this tensor satisfy the same linear constraints for the corresponding directions.


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## 1. Introduction

Linear constraints define many important classes of structured matrices (Toeplitz, Hankel, various sparse matrices of special patterns etc.). A combination of Toeplitz and tensor structures was first considered in [3]. The common case of linear constraints along with tensor approximations of two-level matrices was first studied in [6]. Some estimates of tensor ranks were suggested in $[2,10,11]$. The interest to tensor approximations in combination with linear constraints is well justified by their role as a base for construction of fast algorithms in difficult cases, a good example is a superfast algorithm for approximate inversion of two-level Toeplitz matrices recently proposed in [7].

A matrix $A$ of order $n=p_{1} p_{2}$ can be viewed as a matrix composed of blocks $a_{i j}$ of size $p_{2} \times p_{2}$, where the indices $i, j$ run from 1 to $p=p_{1}$. In particular, $A$ can be of the form

$$
\begin{equation*}
A=A_{r}=\sum_{t=1}^{r} U_{t} \otimes V_{t} \tag{1.1}
\end{equation*}
$$

where $U_{t}$ and $V_{t}$ are matrices of order $p_{1}$ and $p_{2}$, respectively, and $\otimes$ denotes the tensor (Kronecker) product of matrices:

$$
U \otimes V=\left[\begin{array}{ccc}
u_{11} V & \cdots & u_{1 p} V \\
\cdots & \cdots & \cdots \\
u_{p 1} V & \cdots & u_{p p} V
\end{array}\right]
$$

[^0]We denote by $\mathscr{T}_{r}=\mathscr{T}_{r}\left(p_{1}, p_{2}\right)$ the set of all matrices of the form (1.1) with real (for definiteness) entries for fixed values of $r$ and $p_{1}, p_{2}$, and we are especially interested in approximations

$$
A \approx A_{r} \in \mathscr{T}_{r}
$$

that minimize the Frobenius norm $\left\|A-A_{r}\right\|_{F}$ (the square root of the sum of squared entries in modulus). If $\|A-B\|_{F}>\left\|A-A_{r}\right\|_{F}$ for all $B \in \mathscr{T}_{k}$ with $k<r$ and $\|A-B\|_{F} \geq\left\|A-A_{r}\right\|_{F}$ for all $B \in \mathscr{T}_{r}$, then the minimizer matrix $A_{r}$ will be called the minimal approximation of tensor rank $r$.

Let us assume that the blocks $a_{i j}$ of a matrix $A$ satisfy linear constraints

$$
\begin{equation*}
\sum_{i=1}^{p} \sum_{j=1}^{p} c_{i j} a_{i j}=0 \tag{1.2}
\end{equation*}
$$

with some fixed scalar coefficients $c_{i j}$. For this case in [6] it was discovered and proved that the entries of each of the matrices $U_{t}$ of any minimal approximation $A_{r}$ are subject to the same constraints (1.2). It follows, for instance, that if $A$ is a block Toeplitz matrix (every block $a_{i j}$ is a function of $i-j$ ) then each of the matrices $U_{t}$ is a Toeplitz matrix. Similarly, if each of the blocks $a_{i j}$ is a Toeplitz matrix then each of the matrices $V_{t}$ ought to be Toeplitz.

In this paper we want to figure out to which extent the result of [6] can be generalized to the case of tensor approximations with an arbitrary fixed number of factors:

$$
\begin{equation*}
A_{r}=\sum_{t=1}^{r} U_{t} \otimes V_{t} \otimes \cdots \otimes W_{t} . \tag{1.3}
\end{equation*}
$$

Let the number of factors in every summand be equal to $s$ and the orders of matrices $U_{t}, V_{t}, \cdots, W_{t}$ be $p=p_{1}, p_{2}, \cdots, p_{s}$, respectively. Then the order of $A_{r}$ is $n=p_{1} p_{2} \cdots p_{s}$. Denote the set of all matrices of the form (1.3) by $\mathscr{T}_{r}^{s}=\mathscr{T}_{r}^{s}\left(p_{1}, p_{2}, \cdots, p_{s}\right)$. For this case matrices $A_{r}$ are used as approximations for a given matrix $A$ of order $n=p_{1} p_{2} \cdots p_{s}$.

The matrix $A$ can be considered as a block matrix consisting of the blocks $a_{i j}, 1 \leq i, j \leq$ $p=p_{1}$. We will prove that from the viewpoint of preservation of linear constraints the case of arbitrary $s$ is analogous to the case $s=2$ : if the equations (1.2) are valid then the minimality of approximation implies that the same relationships (1.2) hold true for each of the matrices $U_{t}$.

One essential difference is still there. Suppose that $A \in \mathscr{T}_{r_{\text {max }}}$ and $A \notin \mathscr{T}_{r}$ whenever $r<r_{\text {max }}$. Then for $s=2$ the minimal approximation is constructed via the singular value decomposition (SVD) for any $1 \leq r \leq r_{\text {max }}$, whereas in the case $s>2$ there could be some values $1<r<r_{\text {max }}$ for which a minimal approximation of tensor rank $r$ does not exist (cf. [5]). Moreover, there are no generalizations of the SVD to the case $s>2$ that keep all the properties of this decomposition in the case $s=2$ (some partial generalizations can be found in $[1,9]$ ), and therefore, some other techniques are needed.

## 2. Minimal decompositions of tensors

It is convenient to reformulate our questions in the terms of approximation of tensors (multi-index arrays). Instead of a matrix $A$ we consider an array of dimension $s$ (tensor) $A=\left[A_{i j \cdots k}\right]$, where the indices $i, j, \cdots, k$ take the values from finite sets $I, J, \cdots, K$. Once the sets $I, J, \cdots, K$ are fixed, we can define the sum of tensors and the multiplication of a tensor by a scalar in a natural way enabling us to consider the set of tensors as a linear space.

The set of arrays $A_{r}$ of the special form

$$
\left(A_{r}\right)_{i j \cdots k}=\sum_{t=1}^{r} U_{i t} V_{j t} \cdots W_{k t}, \quad i \in I, \quad j \in J, \cdots, k \in K
$$

will be denoted by $\mathscr{T}_{r}$. Since the array $A_{r}$ is determined by matrices

$$
U=\left[U_{i t}\right], \quad V=\left[v_{j t}\right], \cdots, \quad W=\left[W_{k t}\right],
$$

we shall write (due to Kruskal [4])

$$
\begin{equation*}
A_{r}=[U, V, \cdots, W]=\sum_{t=1}^{r} U_{t} \otimes V_{t} \otimes \cdots \otimes W_{t} \tag{2.1}
\end{equation*}
$$

and say that $A_{r}$ is the sum of tensor products of one-dimensional arrays (tensors) $U_{t}, V_{t}, \cdots, W_{t}$. We keep the same notation as in (1.3), but the ordering in which the entries of $U_{t}, V_{t}, \cdots, W_{t}$ are indexed is not prescribed and actually does not matter when this notation is used.

A decomposition of an array $A$ of the form

$$
\begin{equation*}
A=\sum_{t=1}^{r} U_{t} \otimes V_{t} \otimes \cdots \otimes W_{t} \tag{2.2}
\end{equation*}
$$

is called minimal decomposition of tensor rank $r$ if $A \in \mathscr{T}_{r}$ but $A \notin \mathscr{T}_{m}$ for any $m<r$.
Lemma 2.1. Any tensor possesses a minimal decomposition.
Proof. Any tensor can be expressed in the form (2.2) with some number of summands $r$. Among all those decompositions we can obviously find one with minimal possible number of summands.

Lemma 2.2. If a decomposition (2.2) is minimal for a tensor $A$, then the tensors

$$
V_{t} \otimes \cdots \otimes W_{t}, \quad 1 \leq t \leq r
$$

are linearly independent.

Proof. From contrary, assume for definiteness that

$$
V_{j 1} \cdots W_{k 1}=\sum_{t=2}^{r} \alpha_{t} V_{j t} \cdots W_{k t}
$$

Then

$$
A_{i j \cdots k}=\sum_{t=2}^{r}\left(U_{i t}+\alpha_{t} U_{i 1}\right) V_{j t} \cdots W_{k t}
$$

Hence, $A \in \mathscr{T}_{r-1}$, which contradicts the minimality of decomposition (2.2).
Theorem 2.1. Assume that a tensor A satisfies linear constraints

$$
\begin{equation*}
\sum_{i \in I} c_{i} A_{i j \cdots k}=0, \quad j \in J, \cdots, \quad k \in K \tag{2.3}
\end{equation*}
$$

and possesses a minimal decomposition (2.2). Then

$$
\begin{equation*}
\sum_{i \in I} c_{i} U_{i t}=0, \quad 1 \leq t \leq r \tag{2.4}
\end{equation*}
$$

Proof. According to (2.3) and (2.2) we find

$$
\sum_{t=1}^{r}\left(\sum_{i \in I} c_{i} U_{i t}\right) V_{j t} \cdots W_{k t}=0
$$

By Lemma 2.2 the tensors $V_{t} \otimes \cdots \otimes W_{t}$ are linearly independent, and the equations (2.4) follow from the fact that a zero linear combination of these tensors must have zero coefficients.

Note that the indices $i, j, \cdots, k$ are equal "in rights", and so Lemma 2.2 and Theorem 2.1 are valid when we consider summation in any of these indices. It stems, for example, that if an $s$-level Toeplitz (cf. $[8,12]$ ) matrix $A=A_{r}$ is written as a sum of $r$ tensor (Kronecker) products of the form (1.3) with the number of factors $s$ and if (1.3) is its minimal decomposition then each of the matrices $U_{t}, V_{t}, \cdots, W_{t}$ is a Toeplitz matrix.

Remark that all assertions of this section are valid for tensors with entries from an arbitrary field.

## 3. Minimal approximations of tensors

By definition,

$$
\|A\|_{F}=\left(\sum_{i \in I} \sum_{j \in J} \cdots \sum_{k \in K}\left|A_{i j \cdots k}\right|^{2}\right)^{1 / 2}
$$

For a given array $A$, an array $A_{r} \in \mathscr{T}_{r}$ is called minimal approximation of tensor rank $r$ if $\left\|A-A_{m}\right\|_{F} \geq\left\|A-A_{r}\right\|_{F}$ for all $m \leq r$ and $\left\|A-A_{m}\right\|_{F}>\left\|A-A_{r}\right\|_{F}$ for all $m<r$.

Lemma 3.1. Given a matrix $\mathscr{A}$ and a matrix $G$ with $r$ linearly independent columns, assume that a matrix $F$ with $r$ columns is such that for any matrix $P$ with $r$ columns

$$
\left\|\mathscr{A}-F G^{\top}\right\|_{F} \leq\left\|\mathscr{A}-P G^{\top}\right\|_{F}
$$

Then $F=\mathscr{A} Z$ for some matrix $Z$.
Proof. Let us write

$$
F=\mathscr{A} Z+H
$$

where $H$ is uniquely defined by the condition

$$
\mathscr{A}^{*} H=0 .
$$

Then

$$
\left\|\mathscr{A}-F G^{\top}\right\|_{F}^{2}=\left\|\left(\mathscr{A}-\mathscr{A} Z G^{\top}\right)-H G^{\top}\right\|_{F}^{2}=\left\|\mathscr{A}-\mathscr{A} Z G^{\top}\right\|_{F}^{2}+\left\|H G^{\top}\right\|_{F}^{2}
$$

It remains to observe that linear independent columns of $G$ cause us to conclude that the equation $\left\|H G^{\top}\right\|_{F}=0$ takes place if and only if $H=0$.

Theorem 3.1. Let a tensor A satisfy linear constraints (2.3) and a tensor $A_{r}$ of the form (2.1) be its minimal approximation of tensor rank $r$. Then the linear constraints (2.4) are valid and the tensor $A_{r}$ satisfies the same linear constraints (2.3).

Proof. Build up a matrix $\mathscr{A}$ from the elements $A_{i j \cdots k}$ arranging them so that the index $i$ points to rows while the columns are marked by the multi-index

$$
v=(j, \cdots, k)
$$

Further, let $A_{r}=[U, V, \cdots, W]$ be a minimal decomposition of tensor $A_{r}$. Let $G$ be a matrix in which the column $t$ contains the entries of the tensor $V_{j t} \cdots W_{k t}$, the row position being defined by the same multi-index $v=(j, \cdots, k)$. Then, as is readily seen,

$$
\left\|A-A_{r}\right\|_{F}=\left\|\mathscr{A}-U G^{\top}\right\|_{F} .
$$

By Lemma 2.2 the columns of $G$ are linearly independent. Therefore, we may apply Lemma 3.1 for the matrices $\mathscr{A}, F=U$ and $G$. In the end we obtain

$$
U=\mathscr{A} Z .
$$

In chime with (2.3) we have

$$
\sum_{i \in I} c_{i} \mathscr{A}_{i v}=0
$$

It follows that

$$
\sum_{i \in I} c_{i} U_{i t}=\sum_{v}\left(\sum_{i \in I} c_{i} \mathscr{A}_{i v}\right) Z_{v t}=0, \quad 1 \leq t \leq r
$$

which completes the proof.

Corollary 3.1. Assume that a matrix $A_{r}$ is a minimal tensor approximation of the form (1.3) for an s-level matrix A whose blocks satisfy linear constraints (1.2). Then the entries of the matrices $U_{t}$ from (1.3) satisfy the same linear constraints (1.2).

Remark that the results obtained are valid for linear constraints defined by summation in any of indices $i, j, \cdots, k$. For example, if we consider summation in indices $j$ and $k$ then linear constraints for the original tensor are maintained for the tensors $V_{t}$ and $W_{t}$ for all $t$.

In conclusion, we would like to stress a nice practical value of our results. Assume that a $d$-level Toeplitz matrix $A$ with the level sizes all equal to $n$ is approximated by a matrix $A_{r}$ of the form (1.3) where the matrices $U_{t}, V_{t}, \cdots, W_{t}$ are of order $n$. If the best possible $r$ term approximation exists and $r$ is minimal possible value for the achieved approximation accuracy, then Theorem 3.1 states that the matrices $U_{t}, V_{t}, \cdots, W_{t}$ are Toeplitz. Hence, all these matrices are determined by $(2 n-1) r$ parameters, instead of $n^{2} r$ parameters, and the whole approximation problem for $A$ reduces exactly to the same approximation problem for a $d$-dimensional array of size $(2 n-1) \times \cdots \times(2 n-1)$.

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