## A Correction and Comments on "Multi-Scale Deep Neural Network (MscaleDNN) for Solving Poisson-Boltzmann Equation in Complex Domains. CiCP, 28(5):1970–2001,2020"

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Received 20 May 2023; Accepted 27 May 2023

**Abstract.** This note provides a correction of a missing weight constant in the MscaleDNN formula and some comments on the performance of the corrected algorithm.

AMS subject classifications: 35Q68, 65N99, 68T07

Key words: Multi-scale DNN, PDE solver, deep learning.

## 1 Correction on a missing weight constant

Our previous paper on the multi-scale deep neural network (MscaleDNN) in [2] contains an error: a constant  $\alpha_i^d$  or its inverse is missing outside  $f_i(\cdot)$  or  $f_{\theta^{n_i}}(\cdot)$  in Eqs. (2.10), (2.11), (2.14) and (2.15). The following text should replace the corresponding paragraphs in [2] to correct this error.

From (2.5), we can apply a simple down-scaling to convert the high frequency region  $A_i$  to a low frequency region. Namely, we define a scaled version of  $\hat{f}_i(\mathbf{k})$  as

$$\widehat{f}_i^{(\text{scale})}(\mathbf{k}) = \widehat{f}_i(\alpha_i \mathbf{k}), \quad \alpha_i > 1,$$
(2.9)

and, correspondingly in the physical space

$$f_i^{(\text{scale})}(\boldsymbol{x}) = f_i \left(\frac{1}{\alpha_i} \boldsymbol{x}\right) \frac{1}{\alpha_i^d}, \qquad (2.10)$$

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or

$$f_i(\boldsymbol{x}) = \alpha_i^d f_i^{(\text{scale})}(\alpha_i \boldsymbol{x}).$$
(2.11)

We can see the low frequency spectrum of the scaled function  $\hat{f}_i^{(\text{scale})}(\mathbf{k})$  if  $\alpha_i$  is chosen large enough, i.e.,

$$\operatorname{supp} \widehat{f}_{i}^{(\operatorname{scale})}(\mathbf{k}) \subset \left\{ \mathbf{k} \in \mathbb{R}^{d}, \, \frac{(i-1)K_{0}}{\alpha_{i}} \leq |\mathbf{k}| \leq \frac{iK_{0}}{\alpha_{i}} \right\}.$$
(2.12)

Using the F-Principle of common DNNs (Ref. [27] in [2]), with  $iK_0/\alpha_i$  being small, we can train a DNN  $f_{\theta^{n_i}}(\mathbf{x})$ , with  $\theta^{n_i}$  denoting the DNN parameters, to learn  $f_i^{(\text{scale})}(\mathbf{x})$  quickly

$$f_i^{(\text{scale})}(\boldsymbol{x}) \sim f_{\theta^{n_i}}(\boldsymbol{x}), \qquad (2.13)$$

which gives an approximation to  $f_i(x)$  immediately

$$f_i(\boldsymbol{x}) \sim \alpha_i^d f_{\theta^{n_i}}(\alpha_i \boldsymbol{x}) \tag{2.14}$$

and to f(x) as well

$$f(\boldsymbol{x}) \sim \sum_{i=1}^{M} \alpha_i^d f_{\theta^{n_i}}(\alpha_i \boldsymbol{x}).$$
(2.15)

## 3 Numerical results with the corrected MscaleDNN (2.15)

In this section, we present several numerical tests on approximation and solving PDEs to demonstrate the necessity of the missing factor  $\alpha_i$  in front of the subnetworks  $f_{\theta_i}(\cdot)$  in (2.15), which results in faster training and lower generalization errors, as shown in Fig. 1 and later sections.

Three networks will be tested: FNN – fully connected neural network; MscaleDNN – the one missing the  $\alpha_i$  weights; MscaleDNN-corrected – the corrected one with weight factor  $\alpha_i$  included. In the comparison tests, we use the same compact activation functions in [2],

$$\phi(x) = \operatorname{ReLU}(x)^2 - 3\operatorname{ReLU}(x-1)^2 + 3\operatorname{ReLU}(x-2)^2 - \operatorname{ReLU}(x-3)^2.$$
(3.1)

## 3.1 Approximation of a 2-D oscillatory function

The target function for the fitting problem is  $u(x,y) = \frac{1}{N^2} \sum_{m=1}^{N} \sum_{n=1}^{N} e^{\sin(2\pi mx)} e^{\cos(2\pi ny)}$ ,  $(x,y) \in [-1,1]^2$ , where N = 20. 5000 training data at each epoch are randomly sampled from  $[-1,1]^2$ . DNNs are trained by the Adam optimizer with a learning rate 0.0001 and initialized with a Glorot-normal. We compare the following different network structures: (1) FNN with a size 2-1600-1600-1600-1; (2) MscaleDNN with eight subnetworks with a size 2-200-200-200-1 each and scales  $\{1,2,4,8,16,32,64,128\}$ ; (3) MscaleDNN-corrected with eight subnetworks with a size 2-200-200-200-1 each and same scales as MscaleDNN.

In Fig. 2, we show the target function and the DNN solutions on fixed x = -0.6 and y = 0.2. The MscaleDNN-corrected performs better than the MscaleDNN and FNN.

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