

## A SIMPLE WAY CONSTRUCTING SYMPLECTIC RUNGE-KUTTA METHODS\*

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### Abstract

With the help of symplecticity conditions of Partitioned Runge-Kutta methods, a simple way constructing symplectic methods is derived. Examples including several classes of high order symplectic Runge-Kutta methods are given, and showed up the relationship between existing high order Runge-Kutta methods.

*Key words:* Symplecticity condition, Partitioned Runge-Kutta method.

### 1. Introduction and Preliminaries

Let  $\Omega$  be a domain in the oriented Euclidean space  $\mathbb{R}^{2d}$  of point  $(p, q) = ((p_1, \dots, p_d)^T, (q_1, \dots, q_d)^T)$ . If  $H(p, q)$  is a sufficiently smooth real function defined in  $\Omega$ , then the Hamiltonian system of differential equations with Hamiltonian  $H(p, q)$  is given by

$$\frac{dp_i}{dt} = -\frac{\partial H}{\partial q_i} =: f_i(p, q), \quad \frac{dq_i}{dt} = \frac{\partial H}{\partial p_i} =: g_i(p, q), \quad 1 \leq i \leq d. \quad (1.1)$$

The integer  $d$  is called the number of degrees of freedom and  $\Omega$  is the phase space. Here we assume that all Hamiltonians considered are autonomous, i.e., time-independent.

**Definition 1.1.** *A one-step method is called symplectic if, as applied to the Hamiltonian system (1.1), the underlying formula generating numerical solutions  $(p^{n+1}, q^{n+1})$  is a symplectic transformation, that is,*

$$\frac{\partial(p^{n+1}, q^{n+1})^T}{\partial(p^n, q^n)} J \frac{\partial(p^{n+1}, q^{n+1})}{\partial(p^n, q^n)} = J, \quad \forall (p^n, q^n) \in \Omega, \quad (1.2)$$

Where  $J = \begin{pmatrix} 0 & I_d \\ -I_d & 0 \end{pmatrix}$  is the standard symplectic matrix.

**Definition 1.2.** *One step of an  $s$ -stage Partitioned Runge-Kutta (PRK) method with stepsize  $h$  and initial values  $(p^n, q^n)$  applied to (1.1) reads*

$$P_i = p^n + h \sum_{j=1}^s a_{ij} F_j(P_j, Q_j), \quad Q_i = q^n + h \sum_{j=1}^s \bar{a}_{ij} G_j(P_j, Q_j), \quad (1.3a)$$

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$$p^{n+1} = p^n + h \sum_{i=1}^s b_i F_i(P_i, Q_i), \quad q^{n+1} = q^n + h \sum_{i=1}^s \bar{b}_i G_i(P_i, Q_i), \quad (1.3b)$$

Where  $a_{ij}, b_i$  and  $\bar{a}_{ij}, \bar{b}_i$  represent two different Runge-Kutta schemes,  $F = (f_1, f_2, \dots, f_d)^T$ ,  $G = (g_1, g_2, \dots, g_d)^T$ .

**Definition 1.3.** The local error of a PRK method (1.3) is defined by

$$\delta_{p_h}(t_n) = p^{n+1} - p(t_n + h), \quad \delta_{q_h}(t_n) = q^{n+1} - q(t_n + h)$$

Where  $(p(t), q(t))$  is the exact solutions of (1.1) passing through  $(p^n, q^n)$  at  $t_n$ .

By definition 1.1, an  $s$ -stage symplectic PRK method can be characterized as follows:<sup>[7],[9],[12]</sup>

**Theorem 1.4.** If the coefficients of an  $s$ -stage PRK method (1.3) satisfy the relation

$$b_i = \bar{b}_i \quad \text{for } i = 1, \dots, s \quad (1.4a)$$

$$b_i \bar{a}_{ij} + \bar{b}_j a_{ji} - b_i \bar{b}_j = 0 \quad \text{for } i, j = 1, \dots, s, \quad (1.4b)$$

then the PRK method is symplectic.

**Remark 1.** Symplectic Runge-Kutta methods are a special case of symplectic PRK methods with coefficients  $\bar{a}_{ij} = a_{ij}, i, j = 1, \dots, s$ .

Starting from a known  $s$ -stage RK method with  $b_i \neq 0 (i = 1, \dots, s)$ , an  $s$ -stage symplectic PRK method can be defined uniquely as follows:<sup>[9]</sup>

**Theorem 1.5.** Suppose that an  $s$ -stage RK method with coefficients  $a_{ij}, b_i \neq 0$  and distinct  $c_i$ , satisfies the following simplifying assumptions

$$\begin{aligned} B(p) : \sum_{i=1}^s b_i c_i^{k-1} &= \frac{1}{k} \quad \text{for } k = 1, 2, \dots, p, \\ C(\eta) : \sum_{j=1}^s a_{ij} c_j^{k-1} &= \frac{c_i^k}{k} \quad \text{for } i = 1, \dots, s, k = 1, \dots, \eta, \\ D(\zeta) : \sum_{i=1}^s b_i c_i^{k-1} a_{ij} &= \frac{b_j}{k} (1 - c_j^k) \quad \text{for } j = 1, \dots, s, k = 1, \dots, \zeta, \end{aligned}$$

then the  $s$ -stage PRK method with coefficients  $a_{ij}, \bar{b}_i = b_i, \bar{c}_i = c_i$  and  $\bar{a}_{ij} = b_j(1 - a_{ji}/b_i)$  is symplectic and satisfies

$$\delta_{p_h}(t_n) = O(h^{r+1}), \quad \delta_{q_h}(t_n) = O(h^{r+1}),$$

i.e., at least, order  $r = \min(p, 2\eta + 2, 2\zeta + 2, \eta + \zeta + 1)$ .

**Remark 2.** By using the  $W$ -transformation of Hairer and Wanner<sup>[5]</sup> it can be shown that the RK method with coefficients  $\bar{a}_{ij} = b_j(1 - a_{ji}/b_i), b_i$  and  $c_i$  satisfies  $B(p), C(\zeta)$  and  $D(\eta)$ .

**Remark 3.** Moreover, suppose that the stability functions of RK methods with coefficients  $a_{ij}, \bar{b}_i = b_i, \bar{c}_i = c_i$  and  $\bar{a}_{ij} = b_j(1 - a_{ji}/b_i)$  are respectively  $R(Z)$  and  $\bar{R}(Z)$ , if, the corresponding symplectic PRK method applied to a specially linear Hamiltonian system (referred to as a test equations of linear Hamiltonian systems)

$$\begin{cases} \frac{dp}{dt} = -\lambda p \\ \frac{dq}{dt} = \lambda q, \end{cases}$$

then symplecticity conditions (1.2) become

$$R(-Z)\bar{R}(Z) = 1. \quad (1.5)$$

In particular with a symmetric RK method, then  $R(Z) = \bar{R}(Z)$ , with an  $L$ -stable RK method, then the other is not  $A$ -stable, and with  $\bar{a}_{ij} = a_{ij}$  ( $i, j = 1, \dots, s$ ) then (1.5)<sup>[4]</sup> is symplecticity condition for linear Hamiltonian systems.

Go a step further, let  $a_{ij}^* = \frac{1}{2}(a_{ij} + \bar{a}_{ij}) = \frac{1}{2}(a_{ij} + b_j - b_j a_{ji}/b_i)$ , by Remarks 2 and Butcher's order theorem<sup>[2]</sup>, we immediately obtain:

**Theorem 1.6.** *The  $s$ -stage RK method with coefficients  $a_{ij}^* = \frac{1}{2}(a_{ij} + \bar{a}_{ij}), b_i^* = b_i$  and  $c_j^* = c_j$  is symplectic, and at least satisfies  $B(p), C(\xi)$  and  $D(\xi)$ , i.e., order  $r = \min(p, 2\xi + 1)$ , where  $\xi = \min(\eta, \zeta)$ .*

*Proof.* Since

$$\begin{aligned} & b_i a_{ij}^* + b_j a_{ji}^* - b_i b_j \\ &= \frac{1}{2} b_i (a_{ij} + \bar{a}_{ij}) + \frac{1}{2} b_j (a_{ji} + \bar{a}_{ji}) - b_i b_j \\ &= \frac{1}{2} \{ (b_i \bar{a}_{ij} + b_j a_{ji} - b_i b_j) + (b_i a_{ij} + b_j \bar{a}_{ji} - b_i b_j) \} \\ &= 0 \quad \text{for } i, j = 1, \dots, s, \end{aligned}$$

then the  $s$ -stage RK method is symplectic, the rest of this Theorem is a direct consequence of remarks 2 and Butcher's order Theorem<sup>[2]</sup>.

**Remark 4.** Suppose that an  $s$ -stage RK method with coefficients  $(a_{ij}, b_i, c_i)$  satisfies  $b_i > 0$  ( $i = 1, \dots, s$ ), then the  $s$ -stage symplectic RK method generated by coefficients  $\left( a_{ij}^* = \frac{1}{2} \left( a_{ij} + b_j - \frac{b_j a_{ji}}{b_i} \right), b_i, c_i \right)$  is algebraic stable.

It can be seen from Theorem 1.6. that starting from a known high order RK method with  $b_i \neq 0$ , in order to obtain the high order symplectic RK method, values  $\eta$  and  $\zeta$  in  $C(\eta)$  and  $D(\zeta)$  must be very close, that is  $\eta \sim \zeta$ .

In next section, by Theorem 1.5. and Theorem 1.6., high order symplectic Runge-Kutta methods can be derived very easily starting from known high order RK methods, and Examples given will show up the relationship between existing high order Runge-Kutta methods.

## 2. Construction of Symplectic RK Methods

In this Section examples of constructing several classes of high order symplectic Runge-Kutta methods are given, and will show up the relationship between existing high order RK methods.

Starting from an  $s$ -stage known high order symplectic PRK method (or an  $s$ -stage known high order RK method with coefficients  $(a_{ij}, b_i \neq 0, c_i)$ , satisfying  $B(p), C(\eta)$  and  $D(\zeta)$ , by Theorem 1.5. an  $s$ -stage symplectic PRK method is uniquely defined, here the RK method with coefficients  $(\bar{a}_{ij} = b_j(1 - a_{ji}/b_i), \bar{b}_i = b_i, \bar{c}_i = c_i)$ , satisfies  $(B(p), C(\zeta), D(\eta))$ , and then let  $a_{ij}^* = \frac{1}{2}(a_{ij} + \bar{a}_{ij})$ ,  $b_i^* = b$  and  $c_i^* = c_i$ , by Theorem 1.6., then the  $s$ -stage RK method with coefficients  $(a_{ij}^*, b_i^*, c_i^*)$  is symplectic and, at least, satisfies  $B(p), C(\xi)$  and  $D(\xi)$ , i.e., order  $r = \min(p, 2\xi + 1)$ ,  $\xi = \min(\zeta, \eta)$ .

**Example 1.** For the  $s$ -stage symplectic PRK method Lobatto IIIA-IIIIB with coefficients  $(A, b, c) - (\bar{A}, b, c)$ , satisfying  $(B(2s - 2), c(s), D(s - 2)) - (B(2s - 2), C(s - 2), D(s))$ , (see [9]) let  $a_{ij}^* = \frac{1}{2}(a_{ij} + \bar{a}_{ij})$  (i.e.,  $A^* = \frac{1}{2}(A + \bar{A})$ ), by Theorem 1.6., then the  $s$ -stage RK method with coefficients  $(A^*, b, c)$  is symplectic and satisfies  $(B(2s - 2), C(s - 2), D(s - 2))$ . In fact, that is Lobatto IIIS method with the special case  $\sigma = \frac{1}{2}$  (see [3]). For example, its members with 2,3 and 4-stage are generated as follows:

$$\begin{array}{c|cc} 0 & 0 \\ \hline \frac{1}{2} & \frac{1}{2} \\ \hline \frac{1}{2} & \frac{1}{2} \end{array} \quad \text{and} \quad \begin{array}{c|cc} \frac{1}{2} & 0 \\ \hline \frac{1}{2} & 0 \\ \hline \frac{1}{2} & \frac{1}{2} \end{array} \quad \Rightarrow \quad \begin{array}{c|cc} \frac{1}{4} & 0 \\ \hline \frac{1}{2} & \frac{1}{4} \\ \hline \frac{1}{2} & \frac{1}{2} \end{array},$$

$$\begin{array}{c|ccc} 0 & 0 & 0 \\ \hline \frac{5}{24} & \frac{1}{3} & -\frac{1}{24} \\ \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \\ \hline \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \end{array} \quad \text{and} \quad \begin{array}{c|ccc} \frac{1}{6} & -\frac{1}{6} & 0 \\ \hline \frac{1}{6} & \frac{1}{3} & 0 \\ \frac{1}{6} & \frac{5}{6} & 0 \\ \hline \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \end{array} \quad \Rightarrow \quad \begin{array}{c|ccc} \frac{1}{12} & -\frac{1}{12} & 0 \\ \hline \frac{3}{16} & \frac{1}{3} & -\frac{1}{48} \\ \frac{1}{6} & \frac{9}{12} & \frac{1}{12} \\ \hline \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \end{array}$$

$$\text{and} \quad \begin{array}{c|cccc} 0 & 0 & 0 & 0 \\ \hline \frac{11+\sqrt{5}}{120} & \frac{25-\sqrt{5}}{120} & \frac{25-13\sqrt{5}}{120} & \frac{-1+\sqrt{5}}{120} \\ \frac{11-\sqrt{5}}{120} & \frac{25+13\sqrt{5}}{120} & \frac{25+\sqrt{5}}{120} & \frac{-1-\sqrt{5}}{120} \\ \frac{1}{12} & \frac{5}{12} & \frac{5}{12} & \frac{1}{12} \\ \hline \frac{1}{12} & \frac{5}{12} & \frac{5}{12} & \frac{1}{12} \end{array} \quad \text{and} \quad \begin{array}{c|cccc} \frac{1}{12} & \frac{-1-\sqrt{5}}{24} & \frac{-1+\sqrt{5}}{24} & 0 \\ \hline \frac{1}{12} & \frac{25+\sqrt{5}}{120} & \frac{25-13\sqrt{5}}{120} & 0 \\ \frac{1}{12} & \frac{25+13\sqrt{5}}{120} & \frac{25-\sqrt{5}}{120} & 0 \\ \frac{1}{12} & \frac{11-\sqrt{5}}{24} & \frac{11+\sqrt{5}}{24} & 0 \\ \hline \frac{1}{12} & \frac{5}{12} & \frac{5}{12} & \frac{1}{12} \end{array}$$

$$\Rightarrow \quad \begin{array}{c|cccc} \frac{1}{24} & \frac{-1-\sqrt{5}}{48} & \frac{-1+\sqrt{5}}{48} & 0 \\ \hline \frac{21+\sqrt{5}}{240} & \frac{5}{24} & \frac{25-13\sqrt{5}}{120} & \frac{-1+\sqrt{5}}{240} \\ \frac{21-\sqrt{5}}{240} & \frac{25+13\sqrt{5}}{120} & \frac{5}{24} & \frac{-1-\sqrt{5}}{240} \\ \frac{1}{12} & \frac{21-\sqrt{5}}{48} & \frac{21+\sqrt{5}}{48} & \frac{1}{24} \\ \hline \frac{1}{12} & \frac{5}{12} & \frac{5}{12} & \frac{1}{12} \end{array}$$

Since  $s$ -stage Lobatto IIIA (or IIIB) method is symmetric, by Remarks 3, then their stability function is all the same.

**Example 2.** For  $s$ -stage symplectic PRK method Lobatto IIIC-III $\bar{C}$  (referred to as III-process by Butcher [1]) with coefficients  $(A, b, c) - (\bar{A}, b, c)$ , all satisfying  $(B(2s - 2), C(s - 1), D(s - 1))$ , (see [11]) let  $a_{ij}^* = \frac{1}{2}(a_{ij} + \bar{a}_{ij})$ , by Theorem 1.6. then the  $s$ -stage RK method with coefficients  $(A^*, b, c)$  is symplectic and, satisfies  $(B(2s - 2), C(s - 1), D(s - 1))$ . In fact, that is Lobatto III E method (see [6], [3]). For example, its members with 2,3 and 4-stage are generated as follows:

$$\left| \begin{array}{cc} \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \\ \hline \frac{1}{2} & \frac{1}{2} \end{array} \right. \text{ and } \left| \begin{array}{cc} 0 & 0 \\ 1 & 0 \\ \hline \frac{1}{2} & \frac{1}{2} \end{array} \right. \implies \left| \begin{array}{cc} \frac{1}{4} & -\frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \\ \hline \frac{1}{2} & \frac{1}{2} \end{array} \right. ,$$

$$\left| \begin{array}{ccc} \frac{1}{6} & -\frac{1}{3} & \frac{1}{6} \\ \frac{1}{6} & \frac{5}{12} & -\frac{1}{12} \\ \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \\ \hline \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \end{array} \right. \text{ and } \left| \begin{array}{ccc} 0 & 0 & 0 \\ \frac{1}{4} & \frac{1}{4} & 0 \\ 0 & 1 & 0 \\ \hline \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \end{array} \right. \implies \left| \begin{array}{ccc} \frac{1}{12} & -\frac{1}{6} & \frac{1}{12} \\ \frac{5}{24} & \frac{4}{12} & -\frac{1}{24} \\ \frac{1}{12} & \frac{5}{6} & \frac{1}{12} \\ \hline \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \end{array} \right.$$

$$\text{and } \left| \begin{array}{cccc} \frac{1}{12} & -\frac{\sqrt{5}}{12} & \frac{\sqrt{5}}{12} & -\frac{1}{12} \\ \frac{1}{12} & \frac{1}{4} & \frac{10-7\sqrt{5}}{60} & \frac{\sqrt{5}}{60} \\ \frac{1}{12} & \frac{10+7\sqrt{5}}{60} & \frac{1}{4} & \frac{-\sqrt{5}}{60} \\ \frac{1}{12} & \frac{5}{12} & \frac{5}{12} & \frac{1}{12} \\ \hline \frac{1}{12} & \frac{5}{12} & \frac{5}{12} & \frac{1}{12} \end{array} \right. \text{ and } \left| \begin{array}{ccc} 0 & 0 & 0 \\ \frac{5+\sqrt{5}}{60} & \frac{1}{6} & \frac{15-7\sqrt{5}}{60} \\ \frac{5-\sqrt{5}}{60} & \frac{15+7\sqrt{5}}{60} & \frac{1}{6} \\ \frac{1}{6} & \frac{5-\sqrt{5}}{12} & \frac{5+\sqrt{5}}{12} \\ \hline \frac{1}{12} & \frac{5}{12} & \frac{5}{12} & \frac{1}{12} \end{array} \right.$$

$$\implies \left| \begin{array}{cccc} \frac{1}{24} & -\frac{\sqrt{5}}{24} & \frac{\sqrt{5}}{24} & -\frac{1}{24} \\ \frac{10+\sqrt{5}}{120} & \frac{5}{24} & \frac{25-14\sqrt{5}}{120} & \frac{\sqrt{5}}{120} \\ \frac{10-\sqrt{5}}{120} & \frac{25+14\sqrt{5}}{120} & \frac{5}{24} & -\frac{\sqrt{5}}{120} \\ \frac{1}{8} & \frac{10-\sqrt{5}}{24} & \frac{10+\sqrt{5}}{24} & \frac{1}{24} \\ \hline \frac{1}{12} & \frac{5}{12} & \frac{5}{12} & \frac{1}{12} \end{array} \right.$$

Since  $s$ -stage Lobatto IIIC method is  $L$ -stable, by Remarks 3, the  $s$ -stage Lobatto III  $\bar{C}$  method (III-process) is not  $A$ -stable.

**Example 3.** Starting from  $s$ -stage Lobatto  $X$  method with transformation matrix

$$X = \begin{pmatrix} \frac{1}{2} & -\xi_1 & & & & \\ \xi_1 & 0 & & & & \\ & & \ddots & & & \\ & & & -\xi_{s-2} & & \\ & & \xi_{s-2} & 0 & -\xi_{s-1}\sigma_1 & \\ & & & \xi_{s-1}\sigma_2 & 0 & \end{pmatrix}$$

where  $\sigma_1 \neq \sigma_2 \neq \frac{1}{b^T P_{s-1}^2(C)}$  (see [10]), by Theorem 1.5. and Theorem 1.6., such method leads to symmetric and symplectic  $s$ -stage Lobatto IIS method satisfying  $(B(2s-2), C(s-2), D(s-2))$  (see [3]).

**Remark 5.** It can be seen from Example 3 that the starting scheme of generating  $s$ -stage Lobatto IIS method is not unique. For example, all taking  $\sigma_1 = 0, \sigma_2 =$  arbitrary real parameter and  $\sigma_2 \neq \sigma_1 \neq 0$  lead to the  $s$ -stage Lobatto IIS method.

**Example 4.** For  $s$ -stage symplectic PRK method Radau  $IA - I\bar{A}$  (referred to as  $I$ -process by Butcher [1]) with coefficients  $(A, b, c) - (\bar{A}, b, c)$ , satisfying  $(B(2s-1), C(s-1), D(s)) - (B(2s-1), C(s), D(s-1))$  (see [11]), let  $a_{ij}^* = \frac{1}{2}(a_{ij} + \bar{a}_{ij})$ , by Theorem 1.6., then the  $s$ -stage RK method with coefficients  $(A^*, b, c)$  is symplectic and satisfies  $(B(2s-1), C(s-1), D(s-1))$ , i.e., what is called  $s$ -stage Radau IB method (see [8]). For example, its members with 1,2 and 3-stage are generated as follows:

$$\begin{array}{c|c} 1 & \\ \hline & 1 \end{array} \quad \text{and} \quad \begin{array}{c|c} 0 & \\ \hline & 1 \end{array} \quad \Rightarrow \quad \begin{array}{c|c} \frac{1}{2} & \\ \hline & 1 \end{array}$$

$$\begin{array}{c|cc} \frac{1}{4} & -\frac{1}{4} & \\ \hline \frac{1}{4} & \frac{5}{12} & \\ \frac{1}{4} & \frac{3}{4} & \end{array} \quad \text{and} \quad \begin{array}{c|cc} 0 & 0 & \\ \hline \frac{1}{3} & \frac{1}{3} & \\ \frac{1}{4} & \frac{3}{4} & \end{array} \quad \Rightarrow \quad \begin{array}{c|cc} \frac{1}{8} & -\frac{1}{8} & \\ \hline \frac{7}{24} & \frac{3}{8} & \\ \frac{1}{4} & \frac{3}{4} & \end{array}$$

$$\text{and} \quad \begin{array}{c|ccc} \frac{1}{9} & \frac{-(1+\sqrt{6})}{18} & \frac{-1+\sqrt{6}}{18} & \\ \hline \frac{1}{9} & \frac{88+7\sqrt{6}}{360} & \frac{88-43\sqrt{6}}{360} & \\ \frac{1}{9} & \frac{88+43\sqrt{6}}{360} & \frac{88-7\sqrt{6}}{360} & \\ \hline \frac{1}{9} & \frac{16+\sqrt{6}}{36} & \frac{16-\sqrt{6}}{36} & \end{array} \quad \text{and} \quad \begin{array}{c|ccc} 0 & 0 & 0 & \\ \hline \frac{9+\sqrt{6}}{75} & \frac{24+\sqrt{6}}{120} & \frac{168-73\sqrt{6}}{600} & \\ \frac{9-\sqrt{6}}{75} & \frac{168+73\sqrt{6}}{600} & \frac{24-\sqrt{6}}{120} & \\ \hline \frac{1}{9} & \frac{16+\sqrt{6}}{36} & \frac{16-\sqrt{6}}{36} & \end{array}$$

$$\Rightarrow \quad \begin{array}{c|ccc} \frac{1}{18} & \frac{-1-\sqrt{6}}{36} & \frac{-1+\sqrt{6}}{36} & \\ \hline \frac{52+3\sqrt{6}}{450} & \frac{16+\sqrt{6}}{72} & \frac{472-217\sqrt{6}}{1800} & \\ \frac{52-3\sqrt{6}}{450} & \frac{472+217\sqrt{6}}{1800} & \frac{16-\sqrt{6}}{72} & \\ \hline \frac{1}{9} & \frac{16+\sqrt{6}}{36} & \frac{16-\sqrt{6}}{36} & \end{array}$$

Since  $s$ -stage Radau  $IA$  method is  $L$ -stable, by Remarks 3, the  $s$ -stage Radau  $I\bar{A}$  method ( $I$ -process) is not  $A$ -stable.

**Example 5.** For  $s$ -stage symplectic PRK method Radau  $IIA - II\bar{A}$  (referred to as  $II$ -process by Butcher [1]) with coefficients  $(A, b, c) - (\bar{A}, b, c)$ , satisfying  $(B(2s - 1), C(s), D(s - 1)) - (B(2s - 1), C(s - 1), D(s))$  (see [11]), let  $a_{ij}^* = \frac{1}{2}(a_{ij} + \bar{a}_{ij})$ , by Theorem 1.6., then the  $s$ -stage RK method with coefficients  $(A^*, b, c)$  is symplectic and satisfies  $(B(2s - 1), C(s - 1), D(s - 1))$ , i.e., what is called the  $s$ -stage Radau IIB method (see [8]). For example, its members with 1,2 and 3-stage are generated as follows:

$$\left| \begin{array}{c|c} 1 & \\ \hline & 1 \end{array} \right. \text{ and } \left| \begin{array}{c|c} 0 & \\ \hline & 1 \end{array} \right. \implies \left| \begin{array}{c|c} \frac{1}{2} & \\ \hline & 1 \end{array} \right.$$

$$\left| \begin{array}{c|cc} \frac{5}{12} & -\frac{1}{12} & \\ \hline \frac{3}{4} & \frac{1}{4} & \\ \hline \frac{3}{4} & \frac{1}{4} & \end{array} \right. \text{ and } \left| \begin{array}{c|cc} \frac{1}{3} & 0 & \\ \hline 1 & 0 & \\ \hline \frac{3}{4} & \frac{1}{4} & \end{array} \right. \implies \left| \begin{array}{c|cc} \frac{3}{8} & -\frac{1}{24} & \\ \hline \frac{7}{8} & \frac{1}{8} & \\ \hline \frac{3}{4} & \frac{1}{4} & \end{array} \right.$$

$$\text{and } \left| \begin{array}{c|ccc} \frac{88-7\sqrt{6}}{360} & \frac{296-169\sqrt{6}}{1800} & \frac{-2+3\sqrt{6}}{225} & \\ \hline \frac{296+169\sqrt{6}}{1800} & \frac{88+7\sqrt{6}}{360} & \frac{-(2+3\sqrt{6})}{225} & \\ \hline \frac{16-\sqrt{6}}{36} & \frac{16+\sqrt{6}}{36} & \frac{1}{9} & \\ \hline \frac{16-\sqrt{6}}{36} & \frac{16+\sqrt{6}}{36} & \frac{1}{9} & \end{array} \right. \text{ and } \left| \begin{array}{c|ccc} \frac{24-\sqrt{6}}{120} & \frac{14-11\sqrt{6}}{120} & 0 & \\ \hline \frac{24+11\sqrt{6}}{120} & \frac{24+\sqrt{6}}{120} & 0 & \\ \hline \frac{6-\sqrt{6}}{12} & \frac{6+\sqrt{6}}{12} & 0 & \\ \hline \frac{16-\sqrt{6}}{36} & \frac{16+\sqrt{6}}{36} & \frac{1}{9} & \end{array} \right.$$

$$\implies \left| \begin{array}{c|ccc} \frac{16-\sqrt{6}}{72} & \frac{328-167\sqrt{6}}{1800} & \frac{-2+3\sqrt{6}}{450} & \\ \hline \frac{328+167\sqrt{6}}{1800} & \frac{16+\sqrt{6}}{72} & \frac{-2-3\sqrt{6}}{450} & \\ \hline \frac{85-10\sqrt{6}}{180} & \frac{85+10\sqrt{6}}{180} & \frac{1}{18} & \\ \hline \frac{16-\sqrt{6}}{36} & \frac{16+\sqrt{6}}{36} & \frac{1}{9} & \end{array} \right.$$

In the same reason as example 4, the  $s$ -stage Radau  $II\bar{A}$  method ( $II$ -process) is not  $A$ -stable.

**Example 6.** For the  $s$ -stage PRK method Gauss  $IA - I\bar{A}$  with coefficients  $(A, b, c) - (\bar{A}, b, c)$ , all satisfying  $(B(2s), C(s - 1), D(s - 1))$  (see [11]), let  $a_{ij}^* = \frac{1}{2}(a_{ij} + \bar{a}_{ij})$ , by Theorem 1.6., then the  $s$ -stage RK method with coefficients  $(A^*, b, c)$  is symplectic and, at least, satisfies  $(B(2s), C(s - 1), D(s - 1))$ . In fact, that is  $s$ -stage Gauss method with order  $2s$ . For example its members with 2 and 3-stage are generated as follows:

$$\left| \begin{array}{c|cc} \frac{1\pm 2\sigma}{4} & \frac{1\mp 2\sigma}{4} - \frac{\sqrt{3}}{6} & \\ \hline \frac{1\mp 2\sigma}{4} + \frac{\sqrt{3}}{6} & \frac{1\pm 2\sigma}{4} & \\ \hline \frac{1}{2} & \frac{1}{2} & \end{array} \right. = \frac{a_{ij}}{a_{ij}^*} \implies \begin{array}{l} (a_{ij}) \text{ (or } \bar{a}_{ij}) \text{ with } \sigma = 0, \\ \text{i.e., Gauss method with order 4.} \\ \sigma > 0 \end{array}$$

$$\text{and } \left| \begin{array}{ccc|c} \frac{5 \pm 8\sigma}{36} & \frac{2 \mp 4\sigma}{9} - \frac{\sqrt{15}}{15} & \frac{5 \pm 8\sigma}{36} - \frac{\sqrt{15}}{30} & \\ \frac{5 \mp 10\sigma}{36} + \frac{\sqrt{15}}{24} & \frac{2 \pm 5\sigma}{9} & \frac{5 \mp 10\sigma}{36} - \frac{\sqrt{15}}{24} & \\ \frac{5 \pm 8\sigma}{36} + \frac{\sqrt{15}}{30} & \frac{2 \mp 4\sigma}{9} + \frac{\sqrt{15}}{15} & \frac{5 \pm 8\sigma}{36} & \\ \hline & \frac{5}{18} & \frac{4}{9} & \frac{5}{18} \end{array} \right. = \frac{a_{ij}}{\bar{a}_{ij}} \quad \sigma > 0$$

$\implies (a_{ij})$  (or  $(\bar{a}_{ij})$ ) with  $\sigma = 0$ , i.e., Gauss method with order 6.

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