

## A NEW ALGORITHM FOR COMPUTING THE INVERSE AND GENERALIZED INVERSE OF THE SCALED FACTOR CIRCULANT MATRIX\*

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### Abstract

A new algorithm for finding the inverse of a nonsingular scaled factor circulant matrix is presented by the Euclid's algorithm. Extension is made to compute the group inverse and the Moore-Penrose inverse of the singular scaled factor circulant matrix. Numerical examples are presented to demonstrate the implementation of the proposed algorithm.

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*Key words:* Scaled factor circulant matrix, Inverse, Group inverse, Moore-Penrose inverse.

### 1. Introduction

Circulant matrices, as an important class of special matrices, have a wide range of interesting applications [12–19]. They have in recent years been applied in many areas, see, e.g., [2, 3, 6, 10, 11, 15, 17]. Scaled circulant permutation matrices and the matrices that commute with them are natural extensions of this well-studied class, see, e.g., [1, 20–23]. In particular, it will be seen that  $r$ -circulant matrices [10, 11] are precisely those matrices commuting with the scaled circulant permutation matrix.

This paper presents an efficient algorithm to compute the inverse of a nonsingular scaled factor circulant matrix or to compute the group inverse and Moore-Penrose inverse of the circulant matrix when it is singular. The algorithm has small computational complexity. It is a notable character of the algorithm that the singularity of the scaled factor circulant matrix need not be priori known.

We define  $\mathcal{R}$  as the scaled circulant permutation matrix, that is,

$$\mathcal{R} = \begin{pmatrix} 0 & d_1 & 0 & \dots & 0 & 0 \\ 0 & 0 & d_2 & \dots & 0 & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & 0 & d_{n-1} \\ d_n & 0 & 0 & \dots & 0 & 0 \end{pmatrix}_{n \times n}. \quad (1.1)$$

This paper deals with the case where  $\mathcal{R}$  is nonsingular ( $d_i \neq 0$  and fixed).

It is easily verified that the polynomial  $g(x) = x^n - d_1 d_2 \dots d_n$  is both the minimal polynomial and the characteristic polynomial of the matrix  $\mathcal{R}$ . In addition,  $\mathcal{R}$  is nondergatory.

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Moreover,  $\mathcal{R}$  is normal if and only if  $|d_1| = |d_2| = \dots = |d_n|$ , where  $|d_i|, i = 1, \dots, n$  denote the modulus of the complex number  $d_i, i = 1, \dots, n$ .

**Definition 1.1.** An  $n \times n$  matrix  $A$  over  $\mathbb{C}$  is called a scaled factor circulant matrix if  $A$  commutes with  $\mathcal{R}$ , that is,

$$A\mathcal{R} = \mathcal{R}A, \tag{1.2}$$

where  $\mathcal{R}$  is given in (1.1).

Let  $\mathcal{RSFCM}_n$  be the set of all complex  $n \times n$  matrices which commute with  $\mathcal{R}$ . In the following, with  $A = \text{scacirc}_{\mathcal{R}}(a_0, a_1, \dots, a_{n-1})$  we denote the scaled factor circulant matrix  $A$  whose first row is  $(a_0, a_1, \dots, a_{n-1})$ . Remark that the first row of  $A$  completely defines the matrix. Indeed, since  $\mathcal{R}$  is nonderogatory, Eq. (1.2) is fulfilled if and only if  $A = f(\mathcal{R})$  for some polynomial  $f$ . Furthermore,  $\mathcal{RSFCM}_n$  is a vector space of dimension  $n$ , and there is a clear one-to-one correspondence between the polynomials of degree at most  $n - 1$  and the numbers  $a_0, \dots, a_{n-1}$ .

For an  $m \times n$  matrix  $A$ , any solution to the matrix equation  $AXA = A$  is called a *generalized inverse* of  $A$ . In addition, if  $X$  satisfies  $X = XAX$ , then  $A$  and  $X$  are said to be semi-inverses, see, e.g., [2].

In this paper we only consider square matrices  $A$ . In [8, p.51] the smallest positive integer  $k$  for which  $\text{rank}(A^{k+1}) = \text{rank}(A^k)$  holds is called the *index* of  $A$ . If  $A$  has index 1, the generalized inverse  $X$  of  $A$  is called the *group inverse*  $A^\#$  of  $A$ . Clearly,  $A$  and  $X$  are group inverses if and only if they are semi-inverses and  $AX = XA$ .

In [4, 5] a semi-inverse  $X$  of  $A$  was considered in which the nonzero eigenvalues of  $X$  are the reciprocals of the nonzero eigenvalue of  $A$ . These matrices were called *spectral inverses*. It was shown in [5] that a nonzero matrix  $A$  has a unique spectral inverse,  $A^s$ , if and only if  $A$  has index 1: when  $A^s$  is the group inverse  $A^\#$  of  $A$ .

## 2. The Properties of the Scaled Factor Circulant Matrix

**Lemma 2.1.** ([1]) If  $\mathcal{R}$  is a scaled circulant permutation matrix, and if  $k$  is a positive integer, then  $\mathcal{R}^k = D^{(k)}C^k$ , where  $D^{(k)}$  is the diagonal matrix whose  $(j, j)$  entry is  $\prod_{t=j}^{j+k-1} d_t$  for  $1 \leq j \leq n$  and  $C = \text{circ}(0, 1, 0, \dots, 0)$  is the circulant permutation. Furthermore,

$$\mathcal{R}^n = \left(\prod_{j=1}^n d_j\right)I_n, \quad \det \mathcal{R} = (-1)^{n-1} \prod_{j=1}^n d_j.$$

Let  $\omega = \exp(\frac{2\pi i}{n})$  be a primitive  $n$ th root of unity. Then  $\omega_j = d\omega^j, j = 0, 1, \dots, n - 1$  are the distinct roots of  $g(x)$ , where  $g(x) = x^n - d_1d_2 \dots d_n$ , and

$$d = \left(\prod_{t=1}^n d_t\right)^{\frac{1}{n}} \neq 0. \tag{2.1}$$

Let  $F$  be the  $n \times n$  unitary Fourier matrix such that

$$F_{ij} = \frac{1}{\sqrt{n}} \omega^{(i-1)(j-1)} \quad \text{for } 1 \leq i, j \leq n. \tag{2.2}$$

Let

$$\Delta = \text{diag}(\delta_1, \delta_2, \dots, \delta_n), \tag{2.3}$$

where the elements  $\delta_j$  of  $\Delta$  are computed by the recursion formula

$$\delta_{j+1} = \frac{d}{d_j} \delta_j, \quad 1 \leq j \leq n, \quad \delta_{n+1} = \delta_1 = 1.$$

**Lemma 2.2.** ([1]) *Let  $A = \text{scacirc}_{\mathcal{R}}(a_0, a_1, \dots, a_{n-1})$  be a scaled factor circulant matrix over the complex field  $\mathbb{C}$ . Then*

$$\sigma(A) = \{\lambda_j | \lambda_j = f(d\omega^j) = a_0 + \sum_{i=1}^{n-1} a_i \left(\prod_{t=1}^i d_t\right)^{-1} (d\omega^j)^i | 0 \leq j \leq n-1\} \quad (2.4)$$

is the spectrum of  $A$  and

$$A = f(\mathcal{R}) = a_0 I + \sum_{i=1}^{n-1} a_i \left(\prod_{t=1}^i d_t\right)^{-1} \mathcal{R}^i, \quad (2.5)$$

where

$$f(x) = a_0 + \sum_{i=1}^{n-1} a_i \left(\prod_{t=1}^i d_t\right)^{-1} x^i. \quad (2.6)$$

The polynomial (2.6) will be called the representer of the scaled factor circulant matrix  $A$ .

**Lemma 2.3.** ([1]) *Let  $A = \text{scacirc}_{\mathcal{R}}(a_0, a_1, \dots, a_{n-1})$  be a scaled factor circulant matrix over the complex field  $\mathbb{C}$ . If  $F$  is the Fourier matrix, then*

$$A = (\Delta F) \text{diag}(\lambda_0, \dots, \lambda_i, \dots, \lambda_{n-1}) (\Delta F)^{-1}, \quad (2.7)$$

where  $\Delta$  is given by (2.3) and  $\lambda_j, j = 0, 1, \dots, n-1$  are the eigenvalues of  $A$  given by (2.4).

Let  $D_n$  denote the multiplicative semigroup of all  $n \times n$  diagonal complex matrices. By Lemma 1 in [2, p.27] the mapping

$$A \rightarrow (\Delta F)^{-1} A (\Delta F)$$

is a semigroup isomorphism of  $\mathcal{RSFCM}_n$  onto  $D_n$ , where  $F$  and  $\Delta$  are defined by (2.2) and (2.3), respectively.

Let  $A = \text{scacirc}_{\mathcal{R}}(a_0, a_1, \dots, a_{n-1}) \in \mathcal{RSFCM}_n$  be a scaled factor circulant matrix. Then  $\sigma(A) = \{\lambda_i | i = 0, 1, \dots, n-1\}$  by (2.4). Let

$$T_i = \begin{cases} 0, & \text{if } \lambda_i = 0, \\ 1/\lambda_i, & \text{if } \lambda_i \neq 0, \end{cases}$$

for  $i = 0, 1, \dots, n-1$ . If

$$B = (\Delta F) \text{diag}(T_0, \dots, T_i, \dots, T_{n-1}) (\Delta F)^{-1},$$

then by Theorem 1 of [2],  $B = A^s$ , the spectral inverse of  $A$ .

Since each  $A$  in  $\mathcal{RSFCM}_n$  has index 1,  $A^s$  is also the group inverse  $A^\#$  of  $A$ . Moreover, if  $\mathcal{R}$  is normal, then by Theorem 1 of [2],  $A^s = A^+$ , where  $A^+$  denotes the Moore-Penrose inverse of  $A$ .

We summarize the above discussions in the following theorems.

**Theorem 2.1.** *Let  $A \in M_n$ . Then  $A \in \mathcal{RSFCM}_n$  if and only if  $(\Delta F)^{-1}A(\Delta F)$  is a diagonal matrix. Let  $A \in \mathcal{RSFCM}_n$ . If  $A$  is a singular matrix, then  $A^s = A^\# \in \mathcal{RSFCM}_n$ . If  $\mathcal{R}$  is normal, then  $A^+ \in \mathcal{RSFCM}_n$  and  $A^+ = A^\#$ .*

**Theorem 2.2.** *If  $A = \text{scirc}_{\mathcal{R}}(a_0, a_1, \dots, a_{n-1})$  is nonsingular, then  $f(\omega_j) \neq 0$ , where*

$$f(x) = a_0 + \sum_{i=1}^{n-1} a_i \left( \prod_{t=1}^i d_t \right)^{-1} x^i, \quad \omega_j = d\omega^j, \quad j = 0, 1, \dots, n-1$$

*are the distinct roots of  $g(x)$ . If  $A$  is singular and has  $k$  zero eigenvalues, then there are  $\omega_{i_0}, \omega_{i_1}, \dots, \omega_{i_{k-1}}$ , such that  $f(\omega_{i_j}) = 0$ , for  $j = 0, 1, \dots, k-1$ . Conversely, if there exists  $\omega_k$  satisfying  $f(\omega_k) = 0$ , then the scaled factor circulant matrix  $A$  is singular.*

*Proof.* According to Theorem 2.1, we know that  $(\Delta F)^{-1}A(\Delta F) = D$ , where

$$D = \text{diag}(f(\omega_0), f(\omega_1), \dots, f(\omega_{n-1})),$$

and  $\omega_j = d\omega^j, j = 0, 1, \dots, n-1$  are the distinct roots of  $g(x)$ . Thus  $A\Delta F = \Delta FD$ . Since  $\Delta F$  is a nonsingular matrix, then

$$\text{rank}A = \text{rank}A\Delta F = \text{rank}\Delta FD = \text{rank}D.$$

If there exist  $\omega_{i_0}, \omega_{i_1}, \dots, \omega_{i_{k-1}}$  such that  $f(\omega_{i_j}) = 0$ , for  $j = 0, 1, \dots, k-1$ , then there are  $\omega_{i_k}, \omega_{i_{k+1}}, \dots, \omega_{i_{n-1}}$  such that  $f(\omega_{i_j}) \neq 0$ , for  $j = k, k+1, \dots, n-1$ . Thus  $\text{rank}A = n - k$ .

Conversely, if  $\text{rank}A = n - k$ , then there exist  $\omega_{i_k}, \omega_{i_{k+1}}, \dots, \omega_{i_{n-1}}$  such that  $f(\omega_{i_j}) \neq 0$ , for  $j = k, k+1, \dots, n-1$ . Therefore, there are  $\omega_{i_0}, \omega_{i_1}, \dots, \omega_{i_{k-1}}$  such that  $f(\omega_{i_j}) = 0$ , for  $j = 0, 1, \dots, k-1$ .

In addition, let  $A, B \in \mathcal{RSFCM}_n$ . Then  $AB = BA \in \mathcal{RSFCM}_n$ . If  $A$  is a nonsingular matrix, then  $A^{-1} \in \mathcal{RSFCM}_n$ . Thus  $\mathcal{RSFCM}_n$  is a ring.

Polynomial ring has an intimate relation to the scaled factor circulant matrix ring. Let  $P(x)$  be the polynomial ring. For all  $f(x)$  in  $P(x)$ , the degree of  $f(x)$  is denoted by  $\text{deg}(f(x))$ . Let  $P_{n-1}(x)$  be the quotient ring  $P(x)/\langle x^n - d_1d_2 \dots d_n \rangle$ , where  $\langle x^n - d_1d_2 \dots d_n \rangle$  is an ideal. Define  $\varphi$  as a function which maps scaled factor circulant matrix ring onto the polynomial ring by

$$\varphi(A) \mapsto f(x) = a_0 + \sum_{i=1}^{n-1} a_i \left( \prod_{t=1}^i d_t \right)^{-1} x^i,$$

where  $A = \text{scirc}_{\mathcal{R}}(a_0, a_1, \dots, a_{n-1})$ .

Then, we can conclude that  $\varphi$  is a ring isomorphism. The scaled factor circulant matrix ring and the polynomial quotient ring  $P_{n-1}(x)$  are isomorphic. So, if  $A$  is nonsingular, then  $\varphi$  maps the inverse of  $A$  onto the inverse of the representor  $f(x)$  of  $A$ .

### 3. Main Results

**Theorem 3.1.** *Let  $A = \text{scirc}_{\mathcal{R}}(a_0, a_1, \dots, a_{n-1})$  be a scaled factor circulant matrix which is nonsingular, with the representor of  $A$  being*

$$f(x) = a_0 + \sum_{i=1}^{n-1} a_i \left( \prod_{t=1}^i d_t \right)^{-1} x^i.$$

Then there exists a polynomial

$$u(x) = b_0 + \sum_{i=1}^{n-1} b_i \left( \prod_{t=1}^i d_t \right)^{-1} x^i$$

such that  $u(\omega_j) = 1/f(\omega_j)$ , where  $\omega_j, j = 0, 1, \dots, n-1$ , are the roots of  $g(x) = x^n - d_1 d_2 \cdots d_n$  and the inverse of  $A$  is given by

$$B = \text{scacirc}_{\mathcal{R}}(b_0, b_1, \dots, b_{n-1}).$$

*Proof.* From Theorem 2.2, we know that  $f(x) = f(\omega_j) \neq 0, j = 0, 1, \dots, n-1$ . Let

$$g(x) = \prod_{j=0}^{n-1} (x - \omega_j) = x^n - d_1 d_2 \cdots d_n.$$

Then  $f(x)$  and  $g(x)$  are coprime. Hence there exist  $u'(x)$  and  $v(x)$  satisfying

$$f(x)u'(x) + g(x)v(x) = 1.$$

When  $x = \omega_j, j = 0, 1, \dots, n-1$ , then  $g(x) = 0$ . Consequently,  $f(\omega_j)u'(\omega_j) = 1$ . Let

$$u(x) = u'(x) \bmod (x^n - d_1 d_2 \cdots d_n).$$

Then  $\deg(u(x)) < n$ . Since  $\omega_j^n - d_1 d_2 \cdots d_n = 0$ , and  $u(\omega_j) = u'(\omega_j), j = 0, 1, \dots, n-1$ , the existence of  $u(x)$  in Theorem 3.1 is then proved.

For the scaled factor circulant matrix  $B$  we have

$$\begin{aligned} B &= \text{scacirc}_{\mathcal{R}}(b_0, b_1, \dots, b_{n-1}) \\ &= \Delta F \text{diag}(u(\omega_0), u(\omega_1), \dots, u(\omega_{n-1})) (\Delta F)^{-1} \\ &= \Delta F \text{diag}(1/f(\omega_0), 1/f(\omega_1), \dots, 1/f(\omega_{n-1})) (\Delta F)^{-1}. \end{aligned}$$

Consequently,  $BA = I$ . Therefore,  $u(x)$  is the inverse of  $f(x)$  in the quotient ring  $P_{n-1}(x)$ . The polynomial  $u'(x)$  can be obtained by Euclid's Algorithm. This is the main idea of the algorithm for computing the inverse of the scaled factor circulant matrix.

To reduce the computation, suppose  $a$  is the leading coefficient of  $f(x)$  and  $a \neq 0$ , let  $f'(x) = f(x)/a$ . Then  $f(x) = af'(x)$ . The leading coefficient of  $f'(x)$  is 1.

**Theorem 3.2.** Let  $A = \text{scacirc}_{\mathcal{R}}(a_0, a_1, \dots, a_{n-1})$  be a singular scaled factor circulant matrix with the representor

$$f(x) = a_0 + \sum_{i=1}^{n-1} a_i \left( \prod_{t=1}^i d_t \right)^{-1} x^i.$$

Suppose  $A$  has  $m$  nonzero eigenvalues. Without loss of generality, suppose  $f(\omega_j) = 0$ , for  $j = m, m+1, \dots, n-1$ , where  $\omega_j, j = 0, 1, \dots, n-1$ , are roots of  $g(x) = x^n - d_1 d_2 \cdots d_n$ .

Let

$$g_1(x) = \prod_{j=0}^{m-1} (x - \omega_j), \quad g_2(x) = \prod_{j=m}^{n-1} (x - \omega_j), \quad f_1(x) = f(x)g_2(x).$$

Then there exists a polynomial

$$u_1(x) = b'_0 + \sum_{i=1}^{n-1} b'_i \left( \prod_{t=1}^i d_t \right)^{-1} x^i$$

such that  $u_1(\omega_j) = 1/f_1(\omega_j), j = 0, 1, \dots, m-1$ .

Let

$$u(x) = u_1(x)g_2(x) = b_0 + \sum_{i=1}^{n-1} b_i \left( \prod_{t=1}^i d_t \right)^{-1} x^i.$$

Then  $B = \text{scacirc}_{\mathcal{R}}(b_0, b_1, \dots, b_{n-1})$  is the group inverse  $A^\#$  of  $A$ . If  $\mathcal{R}$  is normal, then  $B = \text{scacirc}_{\mathcal{R}}(b_0, b_1, \dots, b_{n-1})$  is the Moore-Penrose inverse  $A^+$  of  $A$ .

*Proof.* Since

$$x^n - d_1 d_2 \cdots d_n = \prod_{j=0}^{n-1} (x - \omega_j),$$

it follows that  $g_1(x)$  and  $g_2(x)$  are coprime. From the condition of Theorem 3.2, we know that  $g_1(x)$  and  $f(x)$  are coprime. So  $f_1(x)$  and  $g_1(x)$  are coprime, and there exist  $u_2(x)$  and  $v(x)$  satisfying

$$f_1(x)u_2(x) + g_1(x)v(x) = 1.$$

When  $x = \omega_j, j = 0, 1, \dots, m-1, g_1(x) = 0$ , thus  $f_1(\omega_j)u_2(\omega_j) = 1$ . Let  $u_1(x) = u_2(x) \bmod (g_1(x))$ . Then the existence of the  $u_1(x)$  in Theorem 3.2 has been proved.

Since  $u(x) = u_1(x)g_2(x)$ , when  $j = m, m+1, \dots, n-1, u(\omega_j) = 0$ , when  $j = 0, 1, \dots, m-1,$

$$u(\omega_j) = u_1(\omega_j)g_2(\omega_j) = g_2(\omega_j)/f_1(\omega_j) = 1/f(\omega_j).$$

The scaled factor circulant matrix  $B$  is given by

$$\begin{aligned} B &= \text{scacirc}_{\mathcal{R}}(b_0, b_1, \dots, b_{n-1}) \\ &= \Delta F \text{diag}(u(\omega_0), u(\omega_1), \dots, u(\omega_{n-1})) (\Delta F)^{-1} \\ &= \Delta F \text{diag}(1/f(\omega_0), 1/f(\omega_1), \dots, 1/f(\omega_{m-1}), 0, \dots, 0) (\Delta F)^{-1}. \end{aligned}$$

It follows from Theorem 2.1 that  $B$  is the group inverse  $A^\#$  of  $A$ . If  $\mathcal{R}$  is normal, then  $B$  is the Moore-Penrose inverse  $A^+$  of  $A$ .

Theorem 3.2 implies that for computing the group inverse  $A^\#$  and the Moore-Penrose inverse  $A^+$  of the singular scaled factor circulant matrix  $A$ , we only need to invert  $f(x)g_2(x)$  in the quotient ring  $P_{n-1}(x)/\langle g_1(x) \rangle$ .

It can be verified that  $g_2(x)$  is the largest common factor of  $f(x)$  and  $g(x) = x^n - d_1 d_2 \cdots d_n$ . In our computations, if  $\deg(f_1(x)) > \deg(g_1(x))$ , we can do polynomial division  $f_1(x) = g_1(x)s(x) + f_{12}(x)$ . As  $f_{12}(\omega_j) = f_1(\omega_j), j = 0, 1, \dots, m-1, f_1(x)$  can be taken the place by  $f_{12}(x)$ .

A similar device was used in [24] for computing the inverses and the group inverses of FLS  $r$ -circulant matrices.

#### 4. Inverting the Scaled Factor Circulant Matrix

The problem becomes how to evaluate  $u(x), v(x)$  when  $f(x), g(x)$  are known and satisfy  $f(x)u(x) + g(x)v(x) = 1$ . Using Euclid's algorithm:

$$\begin{aligned} g(x) &= q_0(x)f(x) + r_1(x), \\ f(x) &= q_1(x)r_1(x) + r_2(x), \\ r_1(x) &= q_2(x)r_2(x) + r_3(x), \\ &\dots\dots\dots \\ r_{i-1}(x) &= q_i(x)r_i(x) + r_{i+1}(x), \\ &\dots\dots\dots \end{aligned}$$

Let  $v_1(x) = 1, u_1(x) = -q_0(x)$ , then  $r_1(x) = f(x)u_1(x) + g(x)v_1(x)$ . It is obvious that

$$\begin{aligned} r_2(x) &= f(x) - q_1(x)[g(x) - q_0(x)f(x)] \\ &= [1 + q_0(x)q_1(x)]f(x) - g(x)q_1(x). \end{aligned}$$

Let  $v_2(x) = -q_1(x), u_2(x) = 1 + q_0(x)q_1(x)$ . We then have

$$r_2(x) = f(x)u_2(x) + g(x)v_2(x).$$

Suppose

$$r_j(x) = f(x)u_j(x) + g(x)v_j(x),$$

and that  $v_j(x), u_j(x)$  have been computed when  $j = 0, 1, \dots, i$ . Then

$$\begin{aligned} r_{i+1}(x) &= r_{i-1}(x) - q_i(x)r_i(x) \\ &= f(x)u_{i-1}(x) + g(x)v_{i-1}(x) - q_i(x)[f(x)u_i(x) + g(x)v_i(x)] \\ &= f(x)[u_{i-1}(x) - q_i(x)u_i(x)] + g(x)[v_{i-1}(x) - q_i(x)v_i(x)]. \end{aligned}$$

Let  $r_{i+1}(x) = f(x)u_{i+1}(x) + g(x)v_{i+1}(x)$ . Then

$$u_{i+1}(x) = u_{i-1}(x) - q_i(x)u_i(x).$$

Now, we have obtained the recurrence formula for  $u_i(x)$ . So, computing  $u(x)$  is equivalent to computing a sequence of polynomials

$$q_0(x), r_1(x), u_1(x), \dots, q_i(x), r_{i+1}(x), u_{i+1}(x), \dots$$

If  $r_{j+1} = \text{const}$ , then  $u(x) = \frac{u_{j+1}(x)}{r_{j+1}(x)}$ . We can improve the method. If the division of polynomial becomes

$$r_{i-1}(x) = q_i(x)r_i(x) + c_{i+1}r_{i+1}(x),$$

where  $c_{i+1}$  is a nonzero number, then the recurrence formula becomes

$$u_{i+1}(x) = \frac{u_{i-1}(x) - q_i(x)u_i(x)}{c_{i+1}}.$$

Thus, we can make the leading coefficient of  $r_i(x)$  equal to 1 by suitably choosing  $c_i$ .

**Algorithm 4.1.** Given a scaled factor circulant matrix

$$A = \text{scacirc}_{\mathcal{R}}(a_0, a_1, \dots, a_{n-1}),$$

the algorithm computes a scaled factor circulant matrix

$$B = \text{scacirc}_{\mathcal{R}}(b_0, b_1, \dots, b_{n-1}).$$

When  $A$  is nonsingular,  $B$  is the inverse of  $A$ . When  $A$  is singular,  $B$  is the group inverse of  $A$ . If  $\mathcal{R}$  is normal, then  $B$  is the Moore-Penrose inverse  $A^+$  of the scaled factor circulant matrix  $A$ . Let

$$\begin{aligned} f(x) &= a_0 + \sum_{i=1}^{n-1} a_i \left( \prod_{t=1}^i d_t \right)^{-1} x^i, & g(x) &= x^n - d_1 d_2 \cdots d_n, \\ r_{-1}(x) &= g(x), & r_0(x) &= f(x), & u_{-1}(x) &= 0, & u_0(x) &= 1. \end{aligned}$$

Perform the polynomial division with remainder

$$\text{do } \begin{cases} r_{i-1}(x) = q_i(x)r_i(x) + r_{i+1}(x), \\ \text{(let } c_{i+1} \text{ be the leading coefficient of } r_{i+1}(x)\text{)}, \\ r_{i+1}(x) \leftarrow r_{i+1}(x)/c_{i+1}, \\ u_{i+1}(x) \leftarrow [u_{i-1}(x) - q_i(x)u_i(x)]/c_{i+1}, i = 0, 1, \dots \end{cases} \quad (4.1)$$

until  $r_m(x) = 1$  or  $r_m(x) = 0$ .

If  $r_m(x) = 1$ , then  $u_m(x)$  is the representor of  $B$ . Then  $B = u_m(\mathcal{R})$  is the inverse of  $A$ .

If  $r_m(x) = 0$ , then  $r_{m-1}(x)$  is the largest common factor of  $f(x)$  and  $g(x)$ .

Let  $r(x) = r_{m-1}(x)$ ,  $r_{-1}(x) = g(x)/r_{m-1}(x)$ ,  $r_0(x) = f(x)r_{m-1}(x) \bmod(r_{-1}(x))$ ,  $u_{-1}(x) = 0$ ,  $u_0(x) = 1$ , go to (4.1).

Now, if  $r_{m'}(x) = 1$ , then  $u(x) = u_{m'}(x)r(x) \bmod(g(x))$  is the representor of  $B$ . Thus  $B = u(\mathcal{R})$  is the group inverse  $A^\#$  of  $A$ . Moreover, if  $\mathcal{R}$  is normal, then  $B = u(\mathcal{R})$  is the Moore-Penrose inverse  $A^+$  of  $A$ .

## 5. Computational Complexity

If the matrix is nonsingular, the computational complexity is divided into two parts. Suppose that the order of the scaled factor circulant matrix  $A$  is  $n$ ,  $\deg(f(x)) = n - 1$ . First we discuss the computational complexity on the division of polynomials.

$$r_{i-1}(x) = q_i(x)r_i(x) + r_{i+1}(x), r_{i+1}(x) \leftarrow r_{i+1}(x)/c_{i+1}, \quad \text{for } i = 0, 1, 2, \dots$$

It is obvious that the division of polynomials will be done for less than  $n - 1$  times. If it is computed for  $n - 1$  times, then  $\deg(q_i(x)) = 1$ , and the leading coefficient of  $r_i(x)$ ,  $q_i(x)$  is 1. So the division of polynomials involves  $2 \sum_{i=1}^{n-1} i = n^2 + \mathcal{O}(n)$  flops. If it has been computed for less than  $n - 1$  times, although  $\deg(q_i(x)) > 1$ , the times of polynomial division need to be reduced. It can be deduced that this part involves less than  $n^2$  flops.

Second we discuss the computational complexity on the multiplication of polynomials.

$$u_{i+1}(x) \leftarrow [u_{i-1}(x) - q_i(x)u_i(x)]/c_{i+1}, \quad i = 0, 1, 2, \dots$$

From Algorithm 4.1, we know that the multiplication of polynomials will be done for less than  $n - 1$  times. If it has been done for  $n - 1$  times, since  $\deg(q_i(x)) = 1$ , and the leading coefficient



of  $r_i(x), q_i(x)$  is 1, the multiplication of polynomials requires  $2 \sum_{i=1}^{n-1} i = n^2 + \mathcal{O}(n)$  flops. If it has been computed for less than  $n-1$  times, the multiple of division involves less than  $n^2$  flops. So, all the amount of work is  $2n^2$  flops. Thus, when  $\deg(f(x)) = m$ , the algorithm involves  $3nm$  flops. So when  $m \ll n$ , we only require  $\mathcal{O}(n)$  flops, which indicates that the algorithm reduces the computational complexity greatly.

With the same reason, when the scaled factor circulant matrix is singular, the method requires  $4n^2 + \mathcal{O}(n)$  flops to compute the group inverse or the Moore-Penrose inverse.

## 6. Numerical Examples

**Example 6.1.** Let

$$A = \begin{pmatrix} 1 & 3 & 2 & 8 \\ 16 & 1 & 6 & 8 \\ 8 & 8 & 1 & 12 \\ 6 & 2 & 4 & 1 \end{pmatrix}.$$

Is the matrix  $A$  singular or nonsingular? If  $A$  is nonsingular, find the inverse of  $A$ .

Since  $A = \text{scacirc}_{\mathcal{R}}(1, 3, 2, 8) = I + 3\mathcal{R} + \mathcal{R}^2 + \mathcal{R}^3 = f(\mathcal{R})$ , where  $f(x) = 1 + 3x + x^2 + x^3$  is the representor of  $A$ , and

$$\mathcal{R} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 4 \\ 2 & 0 & 0 & 0 \end{pmatrix},$$

it is known that  $A$  is a scaled factor circulant matrix. Let

$$\begin{aligned} r_{-1}(x) &= g(x) = x^4 - 16, \\ r_0(x) &= f(x) = 1 + 3x + x^2 + x^3, \\ u_{-1}(x) &= 0, \quad u_0(x) = 1. \end{aligned}$$

Using Algorithm 4.1, we have

$$\begin{aligned} q_0(x) &= x - 1, \quad r_1(x) = x^2 - x + \frac{15}{2}, \quad c_1 = -2, \quad u_1(x) = 0.5x - 0.5; \\ q_1(x) &= x + 2, \quad r_2(x) = x + \frac{28}{5}, \quad c_2 = -2.5, \quad u_2(x) = 0.2x^2 + 0.2x - 0.8; \\ q_2(x) &= x - \frac{33}{5}, \quad r_3(x) = 1, \quad c_3 = \frac{2223}{50}, \\ u_3(x) &= -\frac{289}{2223} + \frac{131}{2223}x + \frac{56}{2223}x^2 - \frac{10}{2223}x^3. \end{aligned}$$

Since  $r_3(x) = 1$ ,  $A$  is a nonsingular matrix and  $u_3(x)$  is the representor of  $A^{-1}$ . Then

$$\begin{aligned} A^{-1} &= \text{scacirc}_{\mathcal{R}}\left(-\frac{289}{2223}, \frac{131}{2223}, \frac{112}{2223}, -\frac{80}{2223}\right) \\ &= \frac{1}{2223} \begin{pmatrix} -289 & 131 & 112 & -80 \\ -160 & -289 & 262 & 448 \\ 448 & -80 & -289 & 524 \\ 262 & 112 & -40 & -289 \end{pmatrix}. \end{aligned}$$

**Example 6.2.** Let

$$A = \begin{pmatrix} -4 & -3 & 2 \\ 64 & -4 & -6 \\ -96 & 32 & -4 \end{pmatrix}.$$

Is the matrix  $A$  singular or nonsingular? If  $A$  is singular, find the group inverse of  $A$ .

Since  $A = \text{scacirc}_{\mathcal{R}}(-4, -3, 2) = -4I - 3\mathcal{R} + \mathcal{R}^2 = f(\mathcal{R})$ , where  $f(x) = -4 - 3x + x^2$  is the representor of  $A$ , and

$$\mathcal{R} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 32 & 0 & 0 \end{pmatrix},$$

it is known that  $A$  is a scaled factor circulant matrix. Let  $r'_{-1}(x) = g(x) = x^3 - 64$ ,  $r'_0(x) = f(x) = -4 - 3x + x^2$ . Using Algorithm 4.1, we have

$$q'_0(x) = x + 3, \quad r'_1(x) = x - 4, \quad c'_1 = 13, \quad q'_1(x) = x + 1, \quad r'_2(x) = 0.$$

Then the largest common factor of  $f(x)$  and  $g(x)$  is  $r'_1(x) = x - 4$ . Consequently,  $A$  is a singular matrix. Let

$$r(x) = x - 4, \quad r_{-1}(x) = \frac{g(x)}{x - 4} = x^2 + 4x + 16, \\ r_0(x) = f(x)(x - 4) \bmod (x^2 + 4x + 16) = 36x + 192, \quad u_{-1}(x) = 0, \quad u_0(x) = 1.$$

Using Algorithm 4.1, we have

$$q_0(x) = \frac{1}{36}x - \frac{1}{27}, \quad r_1(x) = 1, \quad c_1 = \frac{208}{9}, \quad u_1(x) = -\frac{1}{832}x + \frac{1}{624}.$$

Consequently,

$$u_1(x)r(x) = -\frac{1}{156} + \frac{1}{156}x - \frac{1}{832}x^2$$

is the representor of  $A^\#$ . Then

$$A^\# = \text{scacirc}_{\mathcal{R}}\left(-\frac{1}{156}, \frac{1}{156}, -\frac{1}{416}\right) = \begin{pmatrix} -\frac{1}{156} & \frac{1}{156} & -\frac{1}{416} \\ -\frac{1}{13} & -\frac{1}{156} & \frac{2}{156} \\ \frac{32}{156} & -\frac{1}{26} & -\frac{1}{156} \end{pmatrix}.$$

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