

## ON INITIAL-BOUNDARY-VALUE PROBLEMS FOR A CLASS OF SYSTEMS OF QUASI-LINEAR EVOLUTION EQUATIONS

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**Abstract** In this paper the initial-boundary-value problems for pseudo-hyperbolic system of quasi-linear equations:

$$\begin{cases} (-1)^M u_{tt} + A(x, t, U, V) u_{x^{2M}tt} = B(x, t, U, V) u_{x^{2M}t} + C(x, t, U, V) u_{x^{2M}} + f(x, t, U, V) \\ u_{x^k}(0, t) = \psi_{0k}(t), \quad u_{x^k}(l, t) = \psi_{1k}(t), \quad k = 0, 1, \dots, M-1 \\ u(x, 0) = \varphi_0(x), \quad u_t(x, 0) = \varphi_1(x) \end{cases}$$

is studied, where  $U = (u, u_x, \dots, u_{x^{2M-1}})$ ,  $V = (u_t, u_{xt}, \dots, u_{x^{2M-1}t})$ ,  $A, B, C$  are  $m \times m$  matrices,  $u, f, \psi_{0k}, \psi_{1k}, \varphi_0, \varphi_1$  are  $m$ -dimensional vector functions. The existence and uniqueness of the generalized solution (in  $H^2(0, T; H^{2M}(0, l))$ ) of the problems are proved.

**Key Words** Pseudo-hyperbolic system of quasi-linear equations of higher order.

**Classification** 35S.

### 1. Formulation of the Problems

In mathematical physics various problems for systems of quasi-linear differential equations of higher order are posed and considered, for example, see [1-2].

The problem to be considered in this paper is the initial-boundary-value problem for the system of quasi-linear pseudo-hyperbolic differential equations of higher order in the space  $H^2(0, T; H^{2M}(0, l))$

$$\begin{cases} (-1)^M u_{tt} + A(x, t, U, V) u_{x^{2M}tt} = B(x, t, U, V) u_{x^{2M}t} \\ \quad + C(x, t, U, V) u_{x^{2M}} + f(x, t, U, V) & (1) \\ u_{x^k}(0, t) = \psi_{0k}(t), \quad u_{x^k}(l, t) = \psi_{1k}(t), \quad k = 0, 1, \dots, M-1 & (2) \\ u(x, 0) = \varphi_0(x), \quad u_t(x, 0) = \varphi_1(x) & (3) \end{cases}$$

where  $A(x, t, U, V)$ ,  $B(x, t, U, V)$  and  $C(x, t, U, V)$  are  $m \times m$  matrices,  $f(x, t, U, V)$  is a  $m$ -dimensional vector function,  $\psi_{0k}(t), \psi_{1k}(t)$  ( $k = 0, 1, \dots, M-1$ ) and  $\varphi_0(x), \varphi_1(x)$  are  $m$ -dimensional vector functions of  $t \in [0, T]$  and  $x \in [0, l]$  respectively.  $U = (u, u_x, \dots, u_{x^{2M-1}})$ ,  $V = (u_t, u_{xt}, \dots, u_{x^{2M-1}t})$ .

## 2. The Initial-Boundary-Value Problems for Equations with Constant Coefficients

We consider the initial-boundary-value problems for

$$\begin{cases} (-1)^M u_{tt} + a_0 u_{x^{2M}tt} = f(x, t), & 0 < t \leq T, & 0 < x < l & (4) \\ u_{x^k}(0, t) = \psi_{0k}(t), & u_{x^k}(l, t) = \psi_{1k}(t), & k = 0, 1, \dots, M - 1 & (5) \\ u(x, 0) = \varphi_0(x), & u_t(x, 0) = \varphi_1(x), & a_0 = \text{const} > 0 & (6) \end{cases}$$

**Theorem 1** Let  $f(x, t) \in L_2(Q_T)$ ,  $\psi_{0k}(t), \psi_{1k}(t) \in H^2(0, T)$  and  $\varphi_0(x), \varphi_1(x) \in H^{2M}(0, l)$  such that

$$\begin{aligned} \varphi_0^{(k)}(0) = \psi_{0k}(0), \quad \varphi_0^{(k)}(l) = \psi_{1k}(0) \quad \varphi_1^{(k)}(0) = \psi'_{0k}(0), \quad \varphi_1^{(k)}(l) = \psi'_{1k}(0), \\ k = 0, 1, \dots, M - 1 \end{aligned} \tag{7}$$

Then, the problems (4), (5) and (6) have precisely one generalized solution  $u(x, t) \in H^2(0, T; H^{2M}(0, l))$  which satisfies the condition (4) in the generalized sense and the conditions (5), (6) in the classical sense. Furthermore, the following estimate holds

$$\begin{aligned} \|u\|_{H^2(0, T; H^{2M}(0, l))} \leq K_1 \{ \|f\|_{L^2(Q_T)} + \|\varphi_0\|_{H^{2M}(0, l)} + \|\varphi_1\|_{H^{2M}(0, l)} \\ + \sum_{k=0}^{M-1} (\|\psi_{0k}\|_{H^2(0, T)} + \|\psi_{1k}\|_{H^2(0, T)}) \} K_1 = \text{const} \end{aligned} \tag{8}$$

For the proof of Theorem 1 we first prove several lemmas.

**Lemma 1** Consider the boundary value problems for the equation

$$\begin{cases} (-1)^M v + a_0 v_{x^{2M}} = f(x, t) & (9) \\ v_{x^k}(0, t) = \psi''_{0k}(t), \quad v_{x^k}(l, t) = \psi''_{1k}(t), & k = 0, 1, \dots, M - 1 & (10) \end{cases}$$

where  $t$  is a parameter. Obviously, the problems (9), (10) possess a unique solution in the space  $C^{2M, 0}(Q_T)$ , if  $f(x, t) \in C(Q_T)$  and  $\psi''_{0k}(t), \psi''_{1k}(t) \in C[0, T]$ .

**Lemma 2** Consider the initial value problem for ordinary differential equation

$$u_{tt} = v(x, t) \tag{11}$$

with initial condition (6), where  $x \in [0, l]$  is a parameter,  $v(x, t)$  is a unique solution of problems (9), (10) in the space  $C^{2M, 0}(Q_T)$ .

If  $\varphi_0(x), \varphi_1(x) \in C^{2M, 0}[0, l]$  satisfy the condition (7), for problem (11), (6) there exists a unique solution in the space  $C^{2M, 0}(Q_T)$ .

**Proof**

$$u(x, t) = \varphi_0(x) + \varphi_1(x)t + \int_0^t \int_0^\tau v(x, y) dy d\tau \tag{12}$$