STRONG SOLUTION OF THE OBSTACLE PROBLEM FOR FULLY NONLINEAR ELLIPTIC EQUATIONS

(Dept. of Math., Peking University)
(Received Jan. 29, 1990)

Abstract In this paper we obtain the existence of $W^{2,\infty}$ solutions of the obstacle problems for fully nonlinear elliptic equations under more general structure conditions than those in [1] by using the mollifier approach, which is also extended in our discussion.

Key Words Strong solution; fully nonlinear elliptic equations; the mollifier approach.

Classification 35J85

1. Introduction

In [1], by using the method of viscosity solution given by P. L. Lions in [2], Hu Bei deals with the obstacle problem for fully nonlinear elliptic equations

$$\begin{cases}
-F(x, u, Du, D^2u) \le 0 & \text{in } \Omega \\
u(x) \le g(x) & \text{in } \Omega \\
(u-g)F(x, u, Du, D^2u) = 0 & \text{in } \Omega \\
u(x) = 0 & \text{on } \partial\Omega
\end{cases}$$
(1.1)

He proves that the above problem has the unique viscosity solution in $W^{1,\infty}(\Omega) \cap C^{2,\alpha}(K_u)$ under the natural structure conditions and the concave condition as in [3], where

$$K_u = \{x \in \Omega | u(x) < g(x)\}$$
 (1.2)

However, while he discussed the strong solutions, in view of the restriction of his method, he studies only the following special form

$$F(x, u, p, r) = F(r) + f(x, u, p)$$
 (1.3)

where F and f are concave in r and p respectively.

The purpose of this note is to get the strong solution of (1.1) under the general structure conditions. We give the new method of $W^{2,\infty}$ estimate for solutions here.

Let Ω be a bounded open domain in R^n and let $\Gamma = \Omega \times R \times R^n \times S^n$, where S^n is the n(n+1)/2-dimensional space made of symmetric matrices of n-order. Assume that the obstacle g(x) is in $C^2(\bar{\Omega})$ and satisfies the consistent condition

(G1)
$$g(x) \ge 0$$
 on $\partial \Omega$

and that F(x, z, p, r) in Γ satisfies the following structure conditions:

(F1) There exists positive constant $\lambda > 0$ such that

$$\lambda |\xi|^2 \leq \frac{\partial F}{\partial r_{ij}} \xi_i \xi_j \leq \lambda \mu_1(|z|) |\xi|^2, \quad \forall \xi \in \mathbb{R}^n$$

(F2) $|F(x,z,p,0)| \le \lambda \mu_2(|z|)(1+|p|^2)$

(F3) $(1+|p|)^{-1}|F_x| + |F_z| + (1+|p|)|F_p| \le \lambda \mu_3(|z|)(1+|p|^2+|r|)$ $|F_{xx}| + |F_{xx}| + |F_{px}| + |F_{zz}| + |F_{zp}| + |F_{pp}| + (1+|r|)[|F_{rx}| + |F_{rz}| + |F_{rp}|]$ $\le \lambda \mu_4(|z|,|p|)(1+|r|)$

(F4) F(x,z,p,r) is concave in r.

(F5) $|F(x,z,p,r) - F(x_0,z_0,p_0,r)|$ $\leq \lambda \mu_5(|z|,|z_0|,|p|,|p_0|)\{|r|(|x-x_0|+|z-z_0|)+|r|^{1-\beta}+1\}$

(F6) F(x, z, p, r) is strictly decreasing in z.

(F7) $F_z(x, z, 0, 0) \le -\lambda \mu_0$

(F7)' $F(x,g(x)+z,\ Dg(x)+p,\ D^2g(x))\operatorname{sgn} z \leq \lambda \mu_0(1+|p|)$

where $\beta \in (0, 1)$ and $\mu_i (i = 1, 2, 3, 4, 5)$ are non-decreasing in their variables and $\mu_0 > 0$ is a constant.

The main results in this paper are the following:

Theorem 1.1 Suppose that $g(\cdot) \in C^2(\bar{\Omega})$ satisfies (G1) and that F satisfies (F1)-(F6), (F7) or (F7)'. Then the obstacle problem (1.1) has the unique solution in $W^{1,\infty} \cap W^{2,\infty}_{loc}(\Omega)$.

Theorem 1.2 Suppose that $\partial \Omega \in C^2$ and

(G2) g(x) > 0 on $\partial \Omega$ or $g(x) \equiv 0$ on $\partial \Omega$

Under the conditions of Theorem 1.1, the obstacle problem (1.1) has the unique solution in $W^{2,\infty}(\Omega)$.

For simplicity, we always suppose $\lambda = 1$.

(1) W ni noission vii 2. Preliminary Lemmas woods and said envoy all

First we often need the following well-known lemma:

Lemma 2.1 (cf [4], Lemma 3.1 on p.161) Let $\varphi : [T_0, T_1] \to \mathbb{R}^+$ be a bounded function, where $T_1 > T_0 \ge 0$. If for any $s, t : T_0 \le t < s \le T_1, \varphi$ satisfies

$$\varphi(t) \le \theta \varphi(s) + A + \frac{B}{(s-t)^{\alpha}}$$
 (2.1)

where $\theta \in (0,1)$ and A,B,α are non-negative constants. Then

$$\varphi(t) \leq C \Big[A + \frac{B}{(s-t)^{\alpha}} \Big] \qquad \text{for all } T_0 \leq t < s \leq T_1 \tag{2.2}$$

where C depends only on θ and α .

In what follows we shall show the fact that the Hölder norm of a function can be described by its mollification, which is first given by N. S. Trudinger (cf [7]). Here we give some further properties to meet our need.